ANNALES
HENRI LEBESGUE

RÉMI CARLES

KLEBER CARRAPATOSO

MATTHIEU HILLAIRET

RIGIDITY RESULTS IN GENERALIZED ISOTHERMAL FLUIDS

RÉSULTATS DE RIGIDITÉ POUR DES FLUIDES ISOTHERMES GÉNÉRALISÉS

ABSTRACT. — We investigate the long-time behavior of solutions to the isothermal Euler, Korteweg or quantum Navier–Stokes equations, as well as generalizations of these equations where the convex pressure law is asymptotically linear near vacuum. By writing the system with a suitable time-dependent scaling we prove that the densities of global solutions display universal dispersion rate and asymptotic profile. This result applies to weak solutions defined in an appropriate way. In the exactly isothermal case, we establish the compactness of bounded sets of such weak solutions, by introducing modified entropies adapted to the new unknown functions.

RÉSUMÉ. — Nous étudions le comportement en temps long des équations d'Euler, Korteweg ou Navier–Stokes quantique compressibles, dans le cas d'une loi de pression isotherme, ainsi que des généralisations à des lois de pression convexes, asymptotiquement linéaires près du

vide. À l'aide d'une réécriture du système faisant intervenir un changement d'échelle dépendant du temps, nous établissons que les densités des solutions globales ont toutes le même taux de dispersion, et le même profil. Ce résultat est valide pour toute solution faible définie de manière adéquate. Dans le cas exactement isotherme, nous montrons la compacité des ensembles bornés de telles solutions faibles, grâce à l'introduction d'entropies modifiées adaptées aux nouvelles fonctions inconnues.

1. Introduction

In the isentropic case $\gamma > 1$, the Euler equation on $\mathbb{R}^d$, $d \geqslant 1$,

$$(1.1) \qquad \begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla(\rho^\gamma) = 0, \end{cases}$$

enjoys the formal conservations of mass,

$$M(t) = \int_{\mathbb{R}^d} \rho(t, x) \mathrm{d}x \equiv M(0),$$

and entropy (or energy),

$$E(t) = \frac{1}{2} \int_{\mathbb{R}^d} \rho(t, x) |u(t, x)|^2 \mathrm{d}x + \frac{1}{\gamma - 1} \int_{\mathbb{R}^d} \rho(t, x)^\gamma \mathrm{d}x \equiv E(0).$$

In general, smooth solutions are defined only locally in time (see [MUK86, Che90, Xin98]). However, for some range of γ, if the initial velocity has a special structure and the initial density is sufficiently small, the classical solution is defined globally in time. In addition the large time behavior of the solution can be described rather precisely, as established in [Ser97]. We restate some results from [Ser97] in the following theorem:

THEOREM 1.1 (From [Ser97]). — *Let $1 < \gamma \leqslant 1 + 2/d$ and $s > d/2 + 1$. There exists $\eta > 0$ such that the following holds.*

(1) *If $\rho_0, u_0 \in H^s(\mathbb{R}^d)$ are such that $\|(\rho_0^{(\gamma-1)/2}, u_0)\|_{H^s(\mathbb{R}^d)} \leqslant \eta$, then the system (1.1) with initial data $\rho(0, x) = \rho_0(x)$ and $u(0, x) = x + u_0(x)$ admits a unique global solution, in the sense that $(\rho, \tilde{u}) \in C([0, \infty); H^s(\mathbb{R}^d))$, where $\tilde{u}(t, x) = u(t, x) - \frac{x}{1+t}$. In addition, there exists $R_\infty, U_\infty \in H^s(\mathbb{R}^d)$ such that*

$$(1.2) \qquad \left\| \left(\rho(t, x) - \frac{1}{t^d} R_\infty\left(\frac{x}{t}\right), u(t, x) - \frac{x}{1+t} - \frac{1}{t} U_\infty\left(\frac{x}{t}\right) \right) \right\|_{L^\infty(\mathbb{R}^d)} \underset{t \to \infty}{\longrightarrow} 0.$$

(2) *Conversely, if $R_\infty, U_\infty \in H^s(\mathbb{R}^d)$ are such that $\|(R_\infty^{(\gamma-1)/2}, U_\infty)\|_{H^s(\mathbb{R}^d)} \leqslant \eta$, then there exists $\rho_0, u_0 \in H^s(\mathbb{R}^d)$ such that the solution to (1.1) with $\rho(0, x) = \rho_0(x)$ and $u(0, x) = x + u_0(x)$ is global in time in the same sense as above, and (1.2) holds.*

In particular, in the frame of small data (in the sense described above), the dispersion

$$\|\rho(t)\|_{L^\infty(\mathbb{R}^d)} \underset{t \to \infty}{\sim} \frac{\|R_\infty\|_{L^\infty(\mathbb{R}^d)}}{t^d}$$

is universal but the asymptotic profile R_∞ can be arbitrary. Typically, given any function $\psi \in \mathcal{S}(\mathbb{R}^d)$, $R_\infty = \epsilon\psi$ will be allowed provided that $\epsilon > 0$ is sufficiently small. For completeness we provide a brief proof of the above theorem in appendix.

We emphasize that the structure of the velocity is crucial: the initial velocity is a small (decaying) perturbation of a linear velocity. In a way, the above result is the Euler generalization of the global existence results for the Burgers equation with expanding data. Refinements of this result can be found in [GS97, Gra98, Ser16].

The isothermal Euler equation corresponds to the value $\gamma = 1$ in (1.1),

$$(1.3) \qquad \begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \kappa \nabla \rho = 0, \quad \kappa > 0. \end{cases}$$

The mass is still formally conserved, and the energy now reads

$$E(t) = \frac{1}{2} \int_{\mathbb{R}^d} \rho(t,x) |u(t,x)|^2 \mathrm{d}x + \int_{\mathbb{R}^d} \rho(t,x) \ln \rho(t,x) \mathrm{d}x \equiv E(0).$$

Unlike in the isentropic case, the energy has an indefinite sign, a property which causes many technical problems. In this paper, we show that the isothermal Euler equation on $\mathbb{R}^d$, $d \geqslant 1$, with asymptotically vanishing density, $\rho(t,\cdot) \in L^1(\mathbb{R}^d)$, displays a specific large time behavior, in the sense that if the solution is global in time, then the density disperses with a rate different from the above one, and possesses a universal asymptotic Gaussian profile. This property remains when the convex pressure law $P(\rho)$ satisfies $P'(0) > 0$, as well as for the Korteweg and quantum Navier–Stokes equations:

$$(1.4) \qquad \begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla P(\rho) = \frac{\varepsilon^2}{2} \rho \nabla \left(\frac{\Delta\sqrt{\rho}}{\sqrt{\rho}} \right) + \nu \operatorname{div}(\rho Du), \end{cases}$$

with $\varepsilon, \nu \geqslant 0$, where Du denotes the symmetric part of the gradient,

$$Du := \frac{1}{2}(\nabla u + {}^t\nabla u).$$

For this system, we still have conservation of mass and the energy

$$(1.5) \qquad E(t) = \frac{1}{2} \int \rho(t,x) |u(t,x)|^2 \mathrm{d}x + \frac{\varepsilon^2}{2} \int \left| \nabla\sqrt{\rho(t,x)} \right|^2 \mathrm{d}x + \int F(\rho(t,x)) \mathrm{d}x,$$

where

$$F(\rho) = \rho \int_1^\rho \frac{P(r)}{r^2} \mathrm{d}r,$$

satisfies

$$\dot{E}(t) = -\nu \int \rho |Du|^2.$$

In the case $\varepsilon = 0$ and $P(\rho) = \kappa\rho$, equation (1.4) is the precise system derived in [BM10], as a correction to the isothermal quantum Euler equation. We emphasize that, because of the lack of positivity of the term F in the energy functional, only the barotropic variant – where $P(\rho) = \kappa\rho^\gamma$ with $\gamma > 1$ – is studied in references. Classically, a Bohm potential (corresponding to the term multiplied by ε in (1.4)) is also added, see [AS18, GLV15, Jün10, VY16b] for instance. In the case where the

dissipation is absent ($\nu = 0$), but with capillarity ($\varepsilon > 0$), we refer to [BGDD07, AM09, AM12, AH17].

A loose statement of our main result reads (a more precise version is provided in the next section, see Theorem 2.11):

THEOREM 1.2. — *Let* (ρ, u) *be a global weak solution to* (1.4) *with initial density/velocity* (ρ_0, u_0) *satisfying*

$$(1 + |x|^2 + |u_0|^2)^{1/2} \sqrt{\rho_0} \in L^2(\mathbb{R}^d).$$

Then there exists a mapping $\tau : [0, \infty) \to [1, \infty)$ *such that*

$$\tau(t) \underset{t \to \infty}{\sim} 2t\sqrt{P'(0)\ln(t)},$$

$$\rho(t, x) \underset{t \to \infty}{\sim} \frac{\|\rho_0\|_{L^1}}{\pi^{d/2}} \frac{\exp(-|x|^2/\tau(t)^2)}{\tau(t)^d} \quad \text{weakly in } L^1(\mathbb{R}^d).$$

Formally, this theorem entails that, in contrast with the isentropic case, the density of solutions to (1.4) disperses as follows :

$$\|\rho(t)\|_{L^\infty(\mathbb{R}^d)} \underset{t \to \infty}{\sim} \frac{\|\rho_0\|_{L^1(\mathbb{R}^d)}}{(2P'(0)\sqrt{\pi})^d} \times \frac{1}{\left(t\sqrt{\ln(t)}\right)^d},$$

with a universal profile. Note however that in the general framework of the theorem, we do not establish an L^∞ estimate like above; such a decay is proven rigorously only in the case of specific initial data considered in Section 3.1 below. This result applies to a notion of "weak solution" that is based on standard a priori estimates satisfied by smooth solutions to (1.4). We make precise the definition of such solutions in the next section, see Definition 2.1.

The main ingredient of the proof is to translate in terms of our isothermal equations a change of unknown functions introduced for the dispersive logarithmic Schrödinger equation in [CG18]. This enables to transform (1.4) into a system with unknowns (R, U) for which the associated energy is positive-definite. A second feature of the new system is that, asymptotically in time, it reads (keeping only the dominating terms):

$$(1.6) \qquad \begin{cases} \partial_t R + \dfrac{1}{\tau^2} \operatorname{div}(RU) = 0, \\ \partial_t(RU) + 2P'(0)yR + P'(0)\nabla R = 0, \end{cases}$$

where τ is the time-dependent scaling mentioned in Theorem 1.2. By taking the divergence of the second equation and replace $\partial_t \operatorname{div}(RU)$ with the first one, we obtain then (keeping again only the dominating terms):

$$\begin{cases} \partial_t R = 0, \\ \partial_t R - P'(0)\mathcal{L}R = 0, \end{cases}$$

where $\mathcal{L}$ is the Fokker–Planck operator $\mathcal{L}R = \Delta R + 2\operatorname{div}(yR)$. In this last system, the first equation implies that R converges to a stationary solution to the second equation. The analysis of the long-time behavior of solutions to this Fokker–Planck equation, as provided in [AMTU01], entails the expected result.

The outline of the paper is as follows. In the next section, we provide rigorous definitions of weak solutions and precise statements for our main result. Section 3 is then devoted to the long-time behavior of solutions to (1.4). In this section, we compute at first explicit solutions to (1.4) with Gaussian densities. These explicit computations motivate the introduction of the change of variable that we use afterwards. In what remains of this section we give an exhaustive proof of the precise version for Theorem 1.2. The long-time analysis mentioned here is based on the a priori existence of solutions. However, in the compressible setting, global existence of solutions is questionable. So, in the last section of the paper, we focus on the notion of weak solutions that we consider. At first, we present the a priori estimates which motivate their definition. We end the paper by proving a sequential compactness result. This sequential compactness property is a cornerstone for the proof of existence of weak solutions, see e.g. [Lio98, Fei04]. As for the large time behavior, we simply state a loose version of our result here (see Theorem 4.10 for the precise statement):

THEOREM 1.3. — *Assume $\nu > 0$, $0 \leqslant \varepsilon \leqslant \nu$, $P(\rho) = \kappa\rho$ with $\kappa > 0$, and let $T > 0$. Let $(\rho_n, u_n)_{n\in\mathbb{N}}$ be a sequence of weak solutions to (1.4) on $(0, T)$, enjoying a suitable notion of energy dissipation, BD-entropy dissipation, and Mellet–Vasseur type inequality. Then up to the extraction of a subsequence, $(\rho_n, u_n)_{n\in\mathbb{N}}$ converges to a weak solution of (1.4) on $(0, T)$.*

It is for the system (2.8) in terms of (R, U), as mentioned above, that fairly natural a priori estimates are required in the above statement. Even though the notions of solution for (1.4) and (2.8) are equivalent (Lemma 2.7 below), we did not find a direct approach to express the pseudo energy, pseudo BD-entropy and Mellet–Vasseur type inequality mentioned above in a direct way in terms of (ρ, u), that is, without resorting to (R, U).

2. Weak solutions and large time behavior

We now state a precise definition regarding the notion of solution that we consider in this paper. Even though, in (1.4), the fluid genuine unknowns are ρ and u, the mathematical theory that we develop in Section 4 suits better to the unknowns $\sqrt{\rho}$ and $\sqrt{\rho}u$. Therefore we state our definition of weak solution in terms of these latter unknowns. Nevertheless, we shall keep these notations, even though no fluid velocity field u underlies the computation of $\sqrt{\rho}u$.

DEFINITION 2.1. — *Let $\nu \geqslant 0$ and $\varepsilon \geqslant 0$. Given $T > 0$, we call weak solution to (1.4) on $(0, T)$ any pair (ρ, u) such that there is a collection $(\sqrt{\rho}, \sqrt{\rho}u, \mathbf{S}_K, \mathbf{T}_N)$ satisfying*

(1) *The following regularities:*

$$(\langle x \rangle + |u|)\sqrt{\rho} \in L^\infty\left(0, T; L^2(\mathbb{R}^d)\right), \quad \text{where } \langle x \rangle = \sqrt{1 + |x|^2},$$

$$(\varepsilon + \nu)\nabla\sqrt{\rho} \in L^\infty\left(0, T; L^2(\mathbb{R}^d)\right),$$

$$\varepsilon \nabla^2\sqrt{\rho} \in L^2(0, T; L^2(\mathbb{R}^d)),$$

$$\sqrt{\nu}\,\mathbf{T}_N \in L^2(0, T; L^2(\mathbb{R}^d)),$$

with the compatibility conditions

$$\sqrt{\rho} \geqslant 0 \text{ a.e. on } (0,T) \times \mathbb{R}^d, \quad \sqrt{\rho} u = 0 \text{ a.e. on } \{\sqrt{\rho} = 0\}.$$

(2) *Euler case* $\varepsilon = \nu = 0$: *The following equations in* $\mathcal{D}'((0,T) \times \mathbb{R}^d)$

$$(2.1) \qquad \begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\sqrt{\rho} u \otimes \sqrt{\rho} u) + \nabla P(\rho) = 0. \end{cases}$$

(3) *Korteweg and Navier–Stokes cases* $\varepsilon + \nu > 0$: *The following equations in* $\mathcal{D}'((0,T) \times \mathbb{R}^d)$

$$(2.2) \qquad \begin{cases} \partial_t \sqrt{\rho} + \operatorname{div}(\sqrt{\rho} u) = \dfrac{1}{2} \operatorname{Trace}(\mathbf{T}_N), \\ \partial_t(\rho u) + \operatorname{div}(\sqrt{\rho} u \otimes \sqrt{\rho} u) + \nabla P(\rho) = \operatorname{div}\left(\nu \sqrt{\rho} \mathbf{S}_N + \dfrac{\varepsilon^2}{2} \mathbf{S}_K\right), \end{cases}$$

with $\mathbf{S}_N$ *the symmetric part of* $\mathbf{T}_N$, *and the compatibility conditions:*

$$(2.3) \qquad \sqrt{\rho} \mathbf{T}_N = \nabla(\sqrt{\rho}\sqrt{\rho} u) - 2\sqrt{\rho} u \otimes \nabla \sqrt{\rho},$$

$$(2.4) \qquad \mathbf{S}_K = \sqrt{\rho} \nabla^2 \sqrt{\rho} - \nabla \sqrt{\rho} \otimes \nabla \sqrt{\rho}.$$

We emphasize that the above definition is essentially the "standard" one, up to the fact that we require $|x|\sqrt{\rho} \in L^\infty(0,T;L^2(\mathbb{R}^d))$. The reason for this assumption will become clear in the Subsection 4.1 where we will recall the *a priori estimates* motivating this definition (see Lemma 2.7, as well as the definition of the pseudo-energy $\mathcal{E}$ in (2.13)).

Several remarks are in order. When the symbol ρ alone appears, it must be understood as $|\sqrt{\rho}|^2$, while when the symbol u appears alone, it is defined by $u = \sqrt{\rho} u / \sqrt{\rho} \, \mathbf{1}_{\sqrt{\rho} > 0}$. Under the compatibility condition of item (1) this yields a well-defined vector-field. As for the stress-tensors involved in the momentum equation (2.2), we emphasize that (2.3) reads formally $\mathbf{T}_N = \sqrt{\rho} \nabla u$.

An originality of the previous definition is that in the case $\varepsilon + \nu > 0$, we do not ask for the continuity equation in terms of ρ but in terms of $\sqrt{\rho}$. However, we prove here that the usual continuity equation as written in (2.2) is a consequence to this definition thanks to the regularity of $\sqrt{\rho}$ and $\sqrt{\rho} u$. This is the content of the following lemma:

LEMMA 2.2. — *Let* $\varepsilon + \nu > 0$. *Assume that* (ρ, u) *is a weak solution to* (2.2) *on* $(0,T)$ *in the sense of Definition 2.1. Then it satisfies*

$$\partial_t \rho + \operatorname{div}(\rho u) = 0 \quad in \ \ \mathcal{D}'((0,T) \times \mathbb{R}^d).$$

Proof. — By definition, we have

$$\partial_t \sqrt{\rho} + \operatorname{div}\left(\sqrt{\rho} u\right) = \frac{1}{2} \operatorname{Trace}(\mathbf{T}_N)$$

Here we note that $\sqrt{\rho} u \in L^\infty(0,T;L^2(\mathbb{R}^d))$ (so that $\operatorname{div}(\sqrt{\rho} u) \in L^\infty(0,T;H^{-1}(\mathbb{R}^d))$). We can then multiply this equation by $\sqrt{\rho} \in L^\infty(0,T;H^1(\mathbb{R}^d))$. We obtain:

$$\partial_t \rho = -2\sqrt{\rho} \operatorname{div}(\sqrt{\rho} u) + \sqrt{\rho} \operatorname{Trace}(\mathbf{T}_N).$$

At this point we remark that, by definition of $\mathbf{T}_N$:

$$\mathrm{div}(\rho u) = \sqrt{\rho}\,\mathrm{Trace}(\mathbf{T}_N) + 2\sqrt{\rho}u \cdot \nabla\sqrt{\rho}$$

and, since $\rho u = \sqrt{\rho}\sqrt{\rho}u$, the products of the identity below are well-defined:

$$\mathrm{div}(\rho u) = \sqrt{\rho}\,\mathrm{div}(\sqrt{\rho}u) + \sqrt{\rho}u \cdot \nabla\sqrt{\rho}.$$

Combining these equation entails

$$\mathrm{div}(\rho u) = 2\sqrt{\rho}\,\mathrm{div}(\sqrt{\rho}u) - \sqrt{\rho}\,\mathrm{Trace}(\mathbf{T}_N).$$

We conclude thus that:

$$\partial_t \rho = -\,\mathrm{div}(\rho u). \qquad \square$$

The assumptions regarding the regularity of the solution actually imply that the mass of any weak solution is constant:

LEMMA 2.3. — *Let $\varepsilon, \nu \geqslant 0$ and (ρ, u) be a solution to (1.4) on the interval $(0, T)$ in the sense of Definition 2.1. Then we have $\rho \in C(0, T; L^1(\mathbb{R}^d))$ and the mass is conserved,*

$$\int_{\mathbb{R}^d} \rho(t, x)\mathrm{d}x = \int_{\mathbb{R}^d} \rho(0, x)\mathrm{d}x, \quad \forall\, t \in [0, T).$$

Proof. — The only point to notice is that the regularity assumed on the solution makes it possible to perform integrations by parts in the continuity equation. The previous lemma shows indeed that whether we consider the Euler equation or the case $\varepsilon + \nu > 0$, we can work at the level of the usual continuity equation. Integrating in space, recall that $\sqrt{\rho}, \sqrt{\rho}u \in L^\infty(0, T; L^2(\mathbb{R}^d))$, hence $\rho u \in L^\infty(0, T; L^1(\mathbb{R}^d))$, and boundary terms at spatial infinity vanish in the integrations by parts. $\square$

2.1. Rewriting of (1.4) with a suitable time-dependent scaling

In the case where the density ρ is defined for all time and is dispersive (in the sense that it goes to zero pointwise), it is natural to examine the behavior of P near 0, since it gives an "asymptotic pressure law" as time goes to infinity. A consequence of our result is that the large time behavior in (1.4) is very different according to $P'(0) > 0$ or $P'(0) = 0$. Herein, we assume that $P \in C^2(0, \infty; \mathbb{R}^+)$ with $P'(0) > 0$ and $P'' \geqslant 0$. Typically, when $P'' \equiv 0$, we recover the isothermal case, $P(\rho) = \kappa\rho$, and we can also consider

$$P(\rho) = \kappa\rho + \sum_{j=1}^N \kappa_j \rho^{\gamma_j}, \quad N \geqslant 1,\ \kappa_j > 0,\ \gamma_j > 1,$$

with no other restriction on γ_j (in any dimension), or even the exotic case $P(\rho) = e^\rho$. The most general class of pressure laws that we shall consider is fixed by the following assumptions:

ASSUMPTION 2.4 (Pressure law). — *The pressure $P \in C^1(\mathbb{R}^+; \mathbb{R}^+) \cap C^2(0, \infty; \mathbb{R}^+)$ is convex ($P''(\rho) \geqslant 0$ for all $\rho > 0$), and satisfies*

$$\kappa := P'(0) > 0.$$

Resuming the approach from [CG18] (the link between Schrödinger equation and Euler–Korteweg equation is formally given by the Madelung transform), we change the unknown functions as follows. Introduce $\tau(t)$ solution of the ordinary differential equation

$$(2.5) \qquad \ddot{\tau} = \frac{2\kappa}{\tau}, \quad \tau(0) = 1, \quad \dot{\tau}(0) = 0.$$

The reason for considering this equation will become clear in Subsection 3.1. We find in [CG18], for slightly more general initial data:

LEMMA 2.5. — *Let $\alpha, \kappa > 0$, $\beta \in \mathbb{R}$. Consider the ordinary differential equation*

$$(2.6) \qquad \ddot{\tau} = \frac{2\kappa}{\tau}, \quad \tau(0) = \alpha, \quad \dot{\tau}(0) = \beta.$$

It has a unique solution $\tau \in C^2(0, \infty)$, and it satisfies, as $t \to \infty$,

$$\tau(t) = 2t\sqrt{\kappa \ln t} \left(1 + \mathcal{O}(\ell(t))\right), \quad \dot{\tau}(t) = 2\sqrt{\kappa \ln t} \left(1 + \mathcal{O}(\ell(t))\right),$$

where

$$\ell(t) := \frac{\ln \ln t}{\ln t}.$$

We sketch the proof of this lemma in Appendix B, without paying attention to the quantitative estimate of the remainder term. We now introduce the Gaussian $\Gamma(y) = e^{-|y|^2}$, and we set

$$(2.7) \qquad \rho(t, x) = \frac{1}{\tau(t)^d} R\left(t, \frac{x}{\tau(t)}\right) \frac{\|\rho_0\|_{L^1}}{\|\Gamma\|_{L^1}}, \quad u(t, x) = \frac{1}{\tau(t)} U\left(t, \frac{x}{\tau(t)}\right) + \frac{\dot{\tau}(t)}{\tau(t)} x,$$

where we denote by y the spatial variable for R and U. Denoting $\theta = \frac{\|\rho_0\|_{L^1}}{\|\Gamma\|_{L^1}}$, (1.4) becomes, in terms of these new unknowns,

$$(2.8) \qquad \begin{cases} \partial_t R + \dfrac{1}{\tau^2} \operatorname{div}(RU) = 0, \\[2mm] \partial_t(RU) + \dfrac{1}{\tau^2} \operatorname{div}(RU \otimes U) + 2\kappa y R + P'\left(\dfrac{\theta R}{\tau^d}\right) \nabla R \\[3mm] \qquad\qquad = \dfrac{\varepsilon^2}{2\tau^2} R \nabla \left(\dfrac{\Delta \sqrt{R}}{\sqrt{R}}\right) + \dfrac{\nu}{\tau^2} \operatorname{div}(RDU) + \dfrac{\nu \dot{\tau}}{\tau} \nabla R. \end{cases}$$

The analogue of Definition 2.1 is the following:

DEFINITION 2.6. — *Let $\nu \geqslant 0$ and $\varepsilon \geqslant 0$. Given $T > 0$, we call weak solution to (2.8) on $(0, T)$ any pair (R, U) such that there exists a collection $(\sqrt{R}, \sqrt{R}U, \mathbb{S}_K, \mathbb{T}_N)$ satisfying*

(1) *The following regularities:*

$$(\langle y \rangle + |U|)\sqrt{R} \in L^\infty\left(0, T; L^2(\mathbb{R}^d)\right),$$
$$(\varepsilon + \nu)\nabla\sqrt{R} \in L^\infty\left(0, T; L^2(\mathbb{R}^d)\right),$$
$$\varepsilon \nabla^2\sqrt{R} \in L^2(0, T; L^2(\mathbb{R}^d)),$$
$$\sqrt{\nu}\, \mathbb{T}_N \in L^2(0, T; L^2(\mathbb{R}^d)),$$

with the compatibility conditions

$$\sqrt{R} \geqslant 0 \text{ a.e. on } (0, T) \times \mathbb{R}^d, \quad \sqrt{R}U = 0 \text{ a.e. on } \{\sqrt{R} = 0\}.$$

(2) Euler case $\varepsilon = \nu = 0$: The following equations in $\mathcal{D}'((0, T) \times \mathbb{R}^d)$

(2.9)
$$\begin{cases} \partial_t R + \dfrac{1}{\tau^2} \operatorname{div}(RU) = 0, \\[2mm] \partial_t(RU) + \dfrac{1}{\tau^2} \operatorname{div}(\sqrt{R}U \otimes \sqrt{R}U) + 2\kappa y R + P'\left(\dfrac{\theta R}{\tau^d}\right) \nabla R = 0. \end{cases}$$

(3) Korteweg and Navier–Stokes cases $\varepsilon + \nu > 0$: The following equations in $\mathcal{D}'((0, T) \times \mathbb{R}^d)$

(2.10)
$$\begin{cases} \partial_t \sqrt{R} + \dfrac{1}{\tau^2} \operatorname{div}(\sqrt{R}U) = \dfrac{1}{2\tau^2} \operatorname{Trace}(\mathbb{T}_N), \\[2mm] \partial_t(RU) + \dfrac{1}{\tau^2} \operatorname{div}(\sqrt{R}U \otimes \sqrt{R}U) + 2\kappa y R + P'\left(\dfrac{\theta R}{\tau^d}\right) \nabla R \\[2mm] \qquad\qquad = \operatorname{div}\left(\dfrac{\nu}{\tau^2}\sqrt{R}\mathbb{S}_N + \dfrac{\varepsilon^2}{2\tau^2}\mathbb{S}_K\right) + \dfrac{\nu\dot{\tau}}{\tau}\nabla R, \end{cases}$$

with $\mathbb{S}_N$ the symmetric part of $\mathbb{T}_N$ and the compatibility conditions:

(2.11)
$$\sqrt{R}\mathbb{T}_N = \nabla(\sqrt{R}\sqrt{R}U) - 2\sqrt{R}U \otimes \nabla\sqrt{R},$$

(2.12)
$$\mathbb{S}_K = \sqrt{R}\nabla^2\sqrt{R} - \nabla\sqrt{R} \otimes \nabla\sqrt{R}.$$

Mimicking the proof of Lemma 2.2, we see that in the case $\varepsilon + \nu > 0$, if (R, U) is a weak solution to (2.10) on $(0, T)$ in the sense of Definition 2.6, then it satisfies

$$\partial_t R + \frac{1}{\tau^2} \operatorname{div}(RU) = 0 \quad \text{in} \ \mathcal{D}'((0, T) \times \mathbb{R}^d).$$

Similarly, the mass of any weak solution is conserved,

$$\int_{\mathbb{R}^d} R(t, y)\mathrm{d}y = \int_{\mathbb{R}^d} R(0, y)\mathrm{d}y.$$

In view of (2.7), we check directly:

LEMMA 2.7 (Equivalence of the notions of solution). — *Let $T > 0$. Then (ρ, u) is a weak solution of (1.4) on $(0, T)$ if and only if (R, U) is a weak solution of (2.8) on $(0, T)$, where (ρ, u) and (R, U) are related through (2.7).*

Remark 2.8. — If in Definition 2.1, we had required only $(1 + |u|)\sqrt{\rho} \in L^\infty(0, T; L^2(\mathbb{R}^d))$, then the above equivalence would not hold. In the same spirit, the change of unknown (2.7) would make the notion of solution rather delicate in the case of the Newtonian Navier–Stokes equation, a case where typically $u \in L^2(0, T; H^1(\mathbb{R}^d))$. More generally, we do not consider velocities enjoying integrability properties, unless the density appears as a weight in the integral.

Remark 2.9. — To complement the previous remark, we emphasize that for the Euler equation (1.1), for $\gamma > 1$, the local existence result by Makino, Ukai and Kawashima [MUK86] requires $u_0 \in H^s(\mathbb{R}^d)$ with $s > d/2 + 1$, while Theorem 1.1 uses the fact that $u_0(x) - x$ is a small H^s function, generalizing the expanding case in Burgers' equation. In the present case, the change of unknown functions (2.7)

implies $u(0, x) = U(0, x)$, and we assume no special property on u_0, since u always comes with $\sqrt{\rho}$ as a multiplying factor in Definition 2.1.

We define the pseudo-energy $\mathcal{E}$ of the system (2.8) by

$$(2.13) \quad \mathcal{E}(t) := \frac{1}{2\tau^2} \int R|U|^2 + \frac{\varepsilon^2}{2\tau^2} \int |\nabla \sqrt{R}|^2 + P'(0) \int (R|y|^2 + R \ln R)$$
$$+ \frac{\tau^d}{\theta} \int G\left(\frac{\theta R}{\tau^d}\right),$$

where

$$G(u) = \int_0^u \int_0^v \frac{P'(\sigma) - P'(0)}{\sigma} \mathrm{d}\sigma \mathrm{d}v,$$

which formally satisfies

$$(2.14) \quad \dot{\mathcal{E}}(t) = -\mathcal{D}(t) - \nu \frac{\dot{\tau}(t)}{\tau(t)^3} \int R(t, y) \operatorname{div} U(t, y) \mathrm{d}y,$$

where the dissipation $\mathcal{D}(t)$ is defined by

$$(2.15) \quad \mathcal{D}(t) := \frac{\dot{\tau}}{\tau^3} \int R|U|^2 + d\frac{\dot{\tau}}{\tau}\tau^d \left(\int \left[P(\sigma) - \sigma P'(0) \right]\Big|_{\sigma = \frac{\theta R}{\tau^d}} \right)$$
$$+ \varepsilon^2 \frac{\dot{\tau}}{\tau^3} \int |\nabla \sqrt{R}|^2 + \frac{\nu}{\tau^4} \int |\mathbb{S}_N|^2.$$

By convexity we have $G \geqslant 0$, and $P(\sigma) \geqslant P'(0)\sigma$ for $\sigma \geqslant 0$, so $\mathcal{D}(t) \geqslant 0$. Note also the identities

$$(2.16) \quad F''(\sigma) = \frac{P'(0)}{\sigma} + G''(\sigma), \quad F(\rho) = P'(0)\rho \ln \rho + G(\rho).$$

Recall the Csiszár–Kullback inequality (see e.g. [ABC$^+$00, Theorem 8.2.7]): for $f, g \geqslant 0$ with $\int_{\mathbb{R}^d} f = \int_{\mathbb{R}^d} g$,

$$\|f - g\|_{L^1(\mathbb{R}^d)}^2 \leqslant 2\|f\|_{L^1(\mathbb{R}^d)} \int f(x) \ln\left(\frac{f(x)}{g(x)}\right) \mathrm{d}x.$$

Writing

$$\int (R|y|^2 + R \ln R) = \int R \ln \frac{R}{\Gamma},$$

the conservation of the mass for R and the definition (2.7) imply that the pseudo-energy $\mathcal{E}$ is non-negative, $\mathcal{E} \geqslant 0$.

As for global solutions, we have the following natural definition:

DEFINITION 2.10. — *Let $\nu \geqslant 0$ and $\varepsilon \geqslant 0$. We call global weak solution to (2.8) any pair (R, U) which, by restriction, yields a weak solution to (2.8) on $(0, T)$ for arbitrary $T > 0$.*

2.2. Main result: large-time behavior of weak solutions to (2.10)

With the previous definitions and remarks, a quantitative and precise statement of Theorem 1.2 reads as follows:

THEOREM 2.11. — *Let $\varepsilon, \nu \geqslant 0$. Assume that P satisfies Assumption 2.4, and let (R, U) be a global weak solution of (2.8), in the sense of Definition 2.10.*

(1) *If $\int_0^\infty \mathcal{D}(t)\,\mathrm{d}t < \infty$, then*

$$\int_{\mathbb{R}^d} yR(t,y)\mathrm{d}y \underset{t\to\infty}{\longrightarrow} 0 \quad \text{and} \quad \left|\int_{\mathbb{R}^d} (RU)(t,y)\mathrm{d}y\right| \underset{t\to\infty}{\longrightarrow} \infty,$$

unless $\int yR(0,y)\mathrm{d}y = \int(RU)(0,y)\mathrm{d}y = 0$, a case where

$$\int_{\mathbb{R}^d} yR(t,y)\mathrm{d}y = \int_{\mathbb{R}^d} (RU)(t,y)\mathrm{d}y \equiv 0.$$

(2) *If $\sup_{t\geqslant 0} \mathcal{E}(t) + \int_0^\infty \mathcal{D}(t)\,\mathrm{d}t < \infty$, then $R(t,\cdot) \rightharpoonup \Gamma$ weakly in $L^1(\mathbb{R}^d)$ as $t \to \infty$.*

(3) *If $\sup_{t\geqslant 0} \mathcal{E}(t) < \infty$ and the energy E defined by (1.5) satisfies $E(t) = o\,(\ln t)$ as $t \to \infty$, then*

$$\int_{\mathbb{R}^d} |y|^2 R(t,y)\mathrm{d}y \underset{t\to\infty}{\longrightarrow} \int_{\mathbb{R}^d} |y|^2 \Gamma(y)\mathrm{d}y.$$

Remark 2.12. — Unlike in Theorem 1.1, no smallness assumption is made on U at $t = 0$ (U may even be linear in space), so there is no such geometrical structure on the initial velocity as in [Ser97, Gra98].

Remark 2.13. — In view of (2.14)–(2.15) and the property $\mathcal{E} \geqslant 0$, the assumptions of point (2) are fairly natural, after noticing that

$$\frac{\dot{\tau}(t)}{\tau(t)^3} \int R\,|\mathrm{div}\,U|\,\mathrm{d}y \leqslant \frac{\dot{\tau}}{\tau}\left(\int R\mathrm{d}y\right)^{1/2}\left(\frac{1}{\tau^4}\int R|\,\mathrm{div}\,U|^2\mathrm{d}y\right)^{1/2}$$

$$\lesssim \frac{\dot{\tau}}{\tau}\left(\int R\mathrm{d}y\right)^{1/2}\sqrt{\mathcal{D}(t)}.$$

Similarly, at least in the case $\nu = 0$, the formal conservation of the energy E defined by (1.5), encompasses the assumption of point (3).

Remark 2.14 (Wasserstein distance). — The points (2) and (3) of Theorem 2.11 imply the large time convergence of R to Γ in the Wasserstein distance W_2, defined, for ν_1 and ν_2 probability measures, by

$$W_p(\nu_1, \nu_2) = \inf\left\{\left(\int_{\mathbb{R}^d \times \mathbb{R}^d} |x - y|^p \mathrm{d}\mu(x,y)\right)^{1/p}; \quad (\pi_j)_\sharp \mu = \nu_j\right\},$$

where μ varies among all probability measures on $\mathbb{R}^d \times \mathbb{R}^d$, and $\pi_j : \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}^d$ denotes the canonical projection onto the j-th factor. This implies, for instance, the convergence of fractional momenta (see e.g. [Vil03, Theorem 7.12])

$$(2.17) \qquad \int |y|^{2s} R(t,y)\mathrm{d}y \underset{t\to\infty}{\longrightarrow} \int |y|^{2s} \Gamma(y)\mathrm{d}y, \quad 0 \leqslant s \leqslant 1.$$

Back to the initial unknowns (ρ, u), Theorem 2.11 and (2.7) yield

$$\rho(t, x) \underset{t\to\infty}{\sim} \frac{\|\rho_0\|_{L^1(\mathbb{R}^d)}}{\pi^{d/2}}\frac{1}{\tau(t)^d}e^{-|x|^2/\tau(t)^2},$$

as announced in Theorem 1.2, where the symbol $\sim$ means that only a weak limit is considered. However, in the special case of Gaussian initial data considered in Section 3.1, it is easy to check that all the assumptions of Theorem 2.11 are satisfied,

and moreover that $R(t, \cdot) \to \Gamma$ strongly in $L^1(\mathbb{R}^d)$. Finally, another consequence of Lemma 2.5, the (proof of the) last point in Theorem 2.11, and (2.7) is

$$\frac{1}{2} \int_{\mathbb{R}^d} \rho(t,x)|u(t,x)|^2 \mathrm{d}x \underset{t\to\infty}{\sim} P'(0)d\|\rho_0\|_{L^1(\mathbb{R}^d)} \ln t \underset{t\to\infty}{\sim} -P'(0) \int_{\mathbb{R}^d} \rho(t,x) \ln \rho(t,x) \mathrm{d}x.$$

This shows that indeed, no a priori information can be directly extracted from the energy E defined in (1.5).

3. From Gaussians to Theorem 2.11

This part of the paper is devoted to the large time behavior of solutions to (1.3) and its variants. We first compute explicit Gaussian solutions and then proceed to the proof of Theorem 2.11.

3.1. Explicit solution

In this section, we resume and generalize some results established in [Yue12, CFY17]. The generalizations concern two aspects: we allow densities and velocities which are not centered at the same point (hence $\overline{x}_j$ and c_j below), and we consider the quantum Navier–Stokes equation.

3.1.1. Euler and Newtonian Navier–Stokes equations

We recall the compressible Euler equation for isothermal fluids on $\mathbb{R}^d$

$$(3.1) \qquad \begin{cases} \partial_t \rho + \mathrm{div}\,(\rho u) = 0, \\ \partial_t(\rho u) + \mathrm{div}(\rho u \otimes u) + \kappa \nabla \rho = 0, \end{cases}$$

where $\kappa > 0$. As noticed in [Yue12], (3.1) has a family of explicit solutions with Gaussian densities and affine velocities centered at the same point. Allowing different initial centers for these quantities leads to considering

$$(3.2) \qquad \rho(0,x) = b_0 e^{-\sum_{j=1}^d \alpha_{0j} x_j^2}, \quad u(0,x) = \begin{pmatrix} \beta_{01} x_1 \\ \vdots \\ \beta_{0d} x_d \end{pmatrix} + \begin{pmatrix} c_{01} \\ \vdots \\ c_{0d} \end{pmatrix},$$

with $b_0, \alpha_{0j} > 0$, $\beta_{0,j}, c_{0,j} \in \mathbb{R}$. Seeking a solution of the form

$$\rho(t,x) = b(t) e^{-\sum_{j=1}^d \alpha_j(t)(x_j - \overline{x}_j)^2}, \quad u(t,x) = \begin{pmatrix} \beta_1(t) x_1 \\ \vdots \\ \beta_d(t) x_d \end{pmatrix} + \begin{pmatrix} c_1(t) \\ \vdots \\ c_d(t) \end{pmatrix},$$

and plugging this ansatz into (3.1), we obtain a set of ordinary differential equations:

$$(3.3) \qquad \dot{\alpha}_j + 2\alpha_j \beta_j = 0, \qquad\qquad \dot{\beta}_j + \beta_j^2 - 2\kappa \alpha_j = 0,$$

$$(3.4) \qquad \dot{\overline{x}}_j = \beta_j \overline{x}_j + c_j, \qquad\qquad \dot{b} = b \sum_{j=1}^d \left(\dot{\alpha}_j \overline{x}_j^2 + 2\alpha_j \overline{x}_j \dot{\overline{x}}_j - 2\alpha_j c_j \overline{x}_j - \beta_j \right),$$

$$(3.5) \qquad \dot{c}_j + \beta_j c_j + 2\kappa \alpha_j \overline{x}_j = 0.$$

Mimicking [LW06], seeking α_j and β_j of the form

$$\alpha_j(t) = \frac{\alpha_{0j}}{\tau_j(t)^2}, \quad \beta_j(t) = \frac{\dot{\tau}_j(t)}{\tau_j(t)},$$

we check that the two equations in (3.3) are satisfied if and only if

$$(3.6) \qquad \ddot{\tau}_j = \frac{2\kappa\alpha_{0j}}{\tau_j}, \quad \tau_j(0) = 1, \quad \dot{\tau}_j(0) = \beta_{0j},$$

and we find

$$b(t) = \frac{b_0}{\prod_{j=1}^d \tau_j(t)}, \quad \overline{x}_j(t) = c_{0j}t, \quad c_j(t) = c_{0j}\left(1 - \frac{\dot{\tau}_j(t)}{\tau_j(t)}t\right).$$

Remark 3.1. — Since the velocity is affine in x, this computation also yields explicit solutions for the isothermal (Newtonian) Navier–Stokes equations, but not for its quantum counterpart, as we will see below.

3.1.2. Korteweg and quantum Navier–Stokes equations

As in [CFY17], we generalize (3.1) by allowing the presence of a Korteweg term ($\varepsilon > 0$), and we extend this contribution by allowing a quantum dissipation (quantum Navier–Stokes equation, when $\nu > 0$). We recall the isothermal Korteweg and quantum Navier–Stokes equations

$$(3.7) \qquad \begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \kappa\nabla\rho = \dfrac{\varepsilon^2}{2}\rho\nabla\left(\dfrac{\Delta\sqrt{\rho}}{\sqrt{\rho}}\right) + \nu\operatorname{div}(\rho D(u)), \end{cases}$$

with $\varepsilon, \nu \geqslant 0$, and where the Korteweg term is also equal to

$$\frac{\varepsilon^2}{4}\nabla\Delta\rho - \varepsilon^2\operatorname{div}\left(\nabla\sqrt{\rho} \otimes \nabla\sqrt{\rho}\right),$$

which is called the Bohm's identity. Proceeding as in the previous subsection, (3.3)–(3.5) become

$$\dot{\alpha}_j + 2\alpha_j\beta_j = 0, \quad \dot{\beta}_j + \beta_j^2 - 2\kappa\alpha_j = \varepsilon^2\alpha_j^2 - \nu\alpha_j\beta_j,$$

$$(3.8) \qquad \dot{\overline{x}}_j = \beta_j\overline{x}_j + c_j, \quad \dot{b} = b\sum_{j=1}^d \left(\dot{\alpha}_j\overline{x}_j^2 + 2\alpha_j\overline{x}_j\dot{\overline{x}}_j - 2\alpha_jc_j\overline{x}_j - \beta_j\right),$$

$$\dot{c}_j + \beta_jc_j + 2\kappa\alpha_j\overline{x}_j = -\varepsilon^2\alpha_j^2\overline{x}_j + \nu\alpha_j\beta_j\overline{x}_j.$$

Again, we seek α_j and β_j of the form

$$\alpha_j(t) = \frac{\alpha_{0j}}{\tau_j^{\varepsilon,\nu}(t)^2}, \quad \beta_j(t) = \frac{\dot{\tau}_j^\varepsilon(t)}{\tau_j^{\varepsilon,\nu}(t)},$$

we check that the two equations in (3.8) are satisfied if and only if

$$(3.9) \qquad \ddot{\tau}_j^{\varepsilon,\nu} = \frac{2\kappa\alpha_{0j}}{\tau_j^{\varepsilon,\nu}} + \varepsilon^2\frac{\alpha_{0j}^2}{(\tau_j^{\varepsilon,\nu})^3} - \nu\alpha_{0j}\frac{\dot{\tau}_j^{\varepsilon,\nu}}{(\tau_j^{\varepsilon,\nu})^2}, \quad \tau_j^{\varepsilon,\nu}(0) = 1, \quad \dot{\tau}_j^{\varepsilon,\nu}(0) = \beta_{0j},$$

and we find, like before,

$$b(t) = \frac{b_0}{\prod_{j=1}^{d} \tau_j^{\varepsilon,\nu}(t)}, \quad \overline{x}_j(t) = c_{0j}t, \quad c_j(t) = c_{0j}\left(1 - \frac{\dot{\tau}_j^{\varepsilon,\nu}(t)}{\tau_j^{\varepsilon,\nu}(t)}t\right).$$

3.1.3. A universal behavior

It is obvious that the Euler equation (3.1) is a particular case of (3.7), by taking $\varepsilon = \nu = 0$. The Korteweg equation ($\nu = 0$) is in turn related to the nonlinear Schrödinger equation, through Madelung transform. In the present case, consider the logarithmic Schrödinger equation in the semi-classical regime,

$$(3.10) \qquad i\varepsilon\partial_t\psi^\varepsilon + \frac{\varepsilon^2}{2}\Delta\psi^\varepsilon = \kappa\ln\left(|\psi^\varepsilon|^2\right)\psi^\varepsilon.$$

The Madelung transform consists in writing the solution as $\psi^\varepsilon = \sqrt{\rho}e^{i\phi/\varepsilon}$, with $\rho \geqslant 0$ and ϕ real-valued. Plugging this form into (3.10) and identifying the real and imaginary parts yields (3.7), with the identification $u = \nabla\phi$. The model (3.10) was introduced in [BBM76], where the authors noticed that this equation possessed explicit (complex) Gaussian solutions: the phase ϕ is then quadratic, hence a velocity $u = \nabla\phi$ which is linear (or affine). For fixed $\varepsilon > 0$, the large time dynamics for (3.10) was studied in [CG18].

As a matter of fact, the presence of a Korteweg ($\varepsilon > 0$) or quantum Navier–Stokes ($\nu > 0$) term does not alter the large time dynamics provided in Lemma 2.5:

LEMMA 3.2. — *Let $\alpha, \kappa > 0$, $\beta \in \mathbb{R}$, and $\varepsilon, \nu \geqslant 0$. Consider*

$$(3.11) \qquad \ddot{\tau}^{\varepsilon,\nu} = \frac{2\kappa}{\tau^{\varepsilon,\nu}} + \frac{\varepsilon^2}{(\tau^{\varepsilon,\nu})^3} - \nu\frac{\dot{\tau}^{\varepsilon,\nu}}{(\tau^{\varepsilon,\nu})^2}, \quad \tau^{\varepsilon,\nu}(0) = \alpha, \quad \dot{\tau}^{\varepsilon,\nu}(0) = \beta.$$

It has a unique solution $\tau^{\varepsilon,\nu} \in C^2(0,\infty)$, and it satisfies, as $t \to \infty$,

$$\tau^{\varepsilon,\nu}(t) \underset{t\to\infty}{\sim} 2t\sqrt{\kappa\ln t}\,, \quad \dot{\tau}^{\varepsilon,\nu}(t) \underset{t\to\infty}{\sim} 2\sqrt{\kappa\ln t}.$$

We present a sketchy proof of Lemma 3.2 in Appendix B.

Lemma 3.2 shows that ε and ν do not influence the large time dynamics in (3.6). In particular,

$$\alpha_j(t) \underset{t\to\infty}{\sim} \left(2t\sqrt{\kappa\ln t}\right)^{-2}, \quad \beta_j(t) \underset{t\to\infty}{\sim} \frac{1}{t}, \quad b(t) \underset{t\to\infty}{\sim} \frac{\|\rho(0)\|_{L^1}}{\pi^{d/2}}\frac{1}{(2t\sqrt{\kappa\ln t})^d},$$

$$\overline{x}_j(t) = c_{0j}t = o\left(\alpha_j(t)\right), \quad c_j(t) \underset{t\to\infty}{\longrightarrow} 0,$$

thus revealing some unexpected universal behavior for the explicit solutions to (3.7). This is an important hint to believe in Theorem 2.11, as well as a precious guide in the computation, in particular in the derivation of the change of unknown functions (2.7).

3.2. Proof of Theorem 2.11

For the end of this section, we consider a pressure P satisfying Assumption 2.4. As a preamble, we prove a useful a priori estimate:

LEMMA 3.3. — *Consider a density $R(t,y)$ and a velocity-field $U(t,y)$. Suppose that the pseudo-energy*

$$\mathcal{E}(t) = \frac{1}{2\tau^2}\int_{\mathbb{R}^d} R|U|^2 + \frac{\varepsilon^2}{2\tau^2}\int_{\mathbb{R}^d}|\nabla\sqrt{R}|^2 + \kappa\int_{\mathbb{R}^d}(R|y|^2 + R\ln R) + \frac{\tau^d}{\theta}\int_{\mathbb{R}^d} G\left(\frac{\theta R}{\tau^d}\right)$$

is bounded from above for positive times, $\mathcal{E}(t) \leqslant \Lambda$ for all $t \geqslant 0$. Then there exists $C_0 > 0$ such that for all $t \geqslant 0$,

$$\frac{1}{2\tau^2}\int_{\mathbb{R}^d} R|U|^2 + \frac{\varepsilon^2}{2\tau^2}\int_{\mathbb{R}^d}|\nabla\sqrt{R}|^2 + \kappa\int_{\mathbb{R}^d} R(1 + |y|^2 + |\ln R|) + \tau^d\int_{\mathbb{R}^d} G\left(\frac{\theta R}{\tau^d}\right) \leqslant C_0.$$

In view of Remark 2.13, the assumption of this lemma is a consequence of the assumptions of Theorem 2.11.

Proof. — We note that since P is convex, $G \geqslant 0$, so all the terms in $\mathcal{E}$ but one are non-negative. The functional

$$\mathcal{E}_+(t) := \frac{1}{2\tau^2}\int R|U|^2 + \frac{\varepsilon^2}{2\tau^2}\int|\nabla\sqrt{R}|^2 + P'(0)\left(\int R|y|^2 + \int_{R\geqslant 1} R\ln R\right) \\ + \frac{\tau^d}{\theta}\int G\left(\frac{\theta R}{\tau^d}\right)$$

is the sum of non-negative terms, and

$$\mathcal{E}_+(t) \leqslant \Lambda + P'(0)\int_{R<1} R\ln\frac{1}{R}.$$

Note that for any $\eta > 0$,

$$\int_{R<1} R\ln\frac{1}{R} \lesssim \int_{\mathbb{R}^d} R^{1-\eta}.$$

Using the interpolation inequality

$$\int_{\mathbb{R}^d} R^{1-\eta} \leqslant C_\eta\|R\|_{L^1(\mathbb{R}^d)}^{1-\eta-d\eta/2}\||y|^2 R\|_{L^1(\mathbb{R}^d)}^{d\eta/2}, \quad 0 < \eta < \frac{2}{d+2},$$

we infer

$$\mathcal{E}_+(t) \leqslant \Lambda + C_\eta P'(0)\|R\|_{L^1(\mathbb{R}^d)}^{1-\eta-d\eta/2}\||y|^2 R\|_{L^1(\mathbb{R}^d)}^{d\eta/2}.$$

Choosing $\eta < 2/(d+2)$ and invoking the boundedness of mass, we deduce that $\mathcal{E}_+(t)$ remains uniformly bounded for $t \geqslant 0$. The lemma follows by recalling the estimate used above,

$$\int_{R<1} R\ln\frac{1}{R} \lesssim \|R\|_{L^1(\mathbb{R}^d)}^{1-\eta-d\eta/2}\||y|^2 R\|_{L^1(\mathbb{R}^d)}^{d\eta/2}. \qquad \square$$

Remark 3.4. — In view of the evolution of $\mathcal{E}$ given by (2.14), and given that the dissipation $\mathcal{D}$ defined by (2.15) is non-negative, the assumptions of Lemma 3.3 are fairly natural. The uniform boundedness of $\mathcal{E}$, consequence of the conclusion of Lemma 3.3, explains why the assumption

$$\int_0^\infty \mathcal{D}(t)\mathrm{d}t < \infty,$$

made in Theorem 2.11, is quite sensible, even without invoking the Csiszár–Kullback inequality to claim that $\mathcal{E} \geqslant 0$.

Proof of Theorem 2.11. — We assume that $(\sqrt{R}, \sqrt{R}U, \mathbb{T}_N, \mathbb{S}_K)$ is a global weak solution of (2.8), in the sense of Definition 2.10.

(1). — The proof of the first point is a rather straightforward consequence of Definition 2.10 and the assumption $\int_0^\infty \mathcal{D}(t)\,\mathrm{d}t < \infty$. Define

$$\mathcal{I}_1(t) = \int_{\mathbb{R}^d} (RU)(t,y)\mathrm{d}y, \quad \mathcal{I}_2(t) = \int_{\mathbb{R}^d} yR(t,y)\mathrm{d}y.$$

Integrating the momentum equation in (2.10) with respect to y (and just setting $\varepsilon = \nu = 0$ in the case of the Euler equation), we find

$$\dot{\mathcal{I}}_1 = -\frac{1}{\tau^2}\int_{\mathbb{R}^d}\mathrm{div}(RU\otimes U) - 2\kappa\mathcal{I}_2 - \frac{\tau^d}{\theta}\int_{\mathbb{R}^d}\nabla P\left(\tfrac{\theta R}{\tau^d}\right) + \frac{\varepsilon^2}{2\tau^2}\int_{\mathbb{R}^d}\mathrm{div}\left(\mathbb{S}_K\right)$$
$$+ \frac{\nu}{\tau^2}\int_{\mathbb{R}^d}\mathrm{div}\left(\sqrt{R}\mathbb{S}_N\right) + \frac{\nu\dot{\tau}}{\tau}\int_{\mathbb{R}^d}\nabla R.$$

In view of Definition 2.10, $RU\otimes U, R \in L^\infty_{\mathrm{loc}}(0,\infty;L^1(\mathbb{R}^d))$ as well as $\varepsilon\mathbb{S}_K, \nu\sqrt{R}\mathbb{S}_N \in L^2_{\mathrm{loc}}(0,\infty;L^1(\mathbb{R}^d))$. On the other hand, the property $\int_0^\infty \mathcal{D}(t)\,\mathrm{d}t < \infty$ yields that $[P(\sigma) - \sigma P'(0)]\,|_{\sigma=\frac{\theta R}{\tau^d}} \in L^1_{\mathrm{loc}}(0,\infty;L^1(\mathbb{R}^d))$. Therefore, all the functions whose divergence or gradient is present above belong to $L^1_{\mathrm{loc}}(0,\infty;L^1(\mathbb{R}^d))$, so integrating by parts in space yields

$$\dot{\mathcal{I}}_1 = -2\kappa\mathcal{I}_2.$$

Similarly, multiplying the continuity equation by y and integrating in space,

$$\dot{\mathcal{I}}_2 = -\frac{1}{\tau^2}\int_{\mathbb{R}^d} y\,\mathrm{div}(RU) = \frac{1}{\tau^2}\int_{\mathbb{R}^d} RU \equiv \frac{1}{\tau^2}\mathcal{I}_1,$$

where we have used the property $R|y||U| \in L^\infty_{\mathrm{loc}}(0,\infty;L^1(\mathbb{R}^d))$, which stems from Definition 2.10 and Cauchy–Schwarz inequality. Therefore,

$$\dot{\mathcal{I}}_1 = -2\kappa\mathcal{I}_2, \quad \dot{\mathcal{I}}_2 = \frac{1}{\tau^2}\mathcal{I}_1.$$

Introducing $J_2 = \tau\mathcal{I}_2$, we readily compute $\ddot{J}_2 = 0$, hence

$$\mathcal{I}_2(t) = \frac{-\mathcal{I}_1(0)t + \mathcal{I}_2(0)}{\tau(t)}, \quad \mathcal{I}_1(t) = \mathcal{I}_1(0) - 2\kappa\int_0^t \mathcal{I}_2(s)\mathrm{d}s.$$

The first point of Theorem 2.11 is then a direct consequence of Lemma 2.5.

(2). — We split the proof of the second point into four steps.

Step 1. — We first obtain an equation satisfied by R only. Since $\partial_t(\tau^2\partial_t R) = -\partial_t\mathrm{div}(RU)$ as well as $\partial_t(\tau^2\partial_t R) = \tau^2\partial_t^2 R + 2\dot{\tau}\tau\partial_t R$, we obtain from (2.8) that

$$\tau^2\partial_t^2 R + 2\dot{\tau}\tau\partial_t R = P'(0)\mathcal{L}R + \frac{1}{\tau^2}\nabla^2 : (RU\otimes U) + \mathrm{div}\left((P'(\tfrac{\theta R}{\tau^d}) - P'(0))\cdot\nabla R\right)$$
$$+ \nabla^2 : \left(\frac{\nu}{\tau^2}\sqrt{R}\mathbb{S}_N + \frac{\varepsilon^2}{2\tau^2}\mathbb{S}_K\right) + \nu\frac{\dot{\tau}}{\tau}\Delta R,$$

where we denote by $\mathcal{L}$ the Fokker–Planck operator $\mathcal{L}R := \Delta_y R + 2\,\mathrm{div}_y(yR)$.

Step 2. — Since $\tau^2 \ll (\tau\dot{\tau})^2$ as $t \to \infty$, it is natural to introduce the new time variable

$$s(t) = P'(0) \int \frac{1}{\tau\dot{\tau}} = \frac{1}{2} \int \frac{\ddot{\tau}}{\dot{\tau}} = \frac{1}{2} \ln \dot{\tau}(t) \underset{t\to\infty}{\sim} \frac{1}{4} \ln \ln t,$$

where the last estimate stems from Lemma 2.5, and we define $\alpha : s \mapsto \alpha(s) = t$. We observe that, thanks to Lemma 2.5, the following asymptotic estimates hold in terms of the s-variable:

$$\tau \circ \alpha(s) \underset{s\to\infty}{\sim} 2\sqrt{P'(0)}e^{2s}e^{e^{4s}}, \quad \dot{\tau} \circ \alpha(s) \underset{s\to\infty}{\sim} 2\sqrt{P'(0)}e^{2s}.$$

Setting $\bar{R}(s,y) = R(t,y)$, $\bar{U}(s,y) = U(t,y)$ and $\bar{\mathbb{T}}_N(s,y) = \mathbb{T}_N(t,y)$, $\bar{\mathbb{S}}_K(s,y) = \mathbb{S}_K(t,y)$, a straightforward computation shows that $\bar{R}$ satisfies

$$\partial_s \bar{R} - \frac{2P'(0)}{(\dot{\tau} \circ \alpha)^2} \partial_s \bar{R} + \frac{P'(0)}{(\dot{\tau} \circ \alpha)^2} \partial_s^2 \bar{R} = \mathcal{L}\bar{R} + \mathcal{N}_\alpha[\bar{R}, \bar{U}, \bar{\mathbb{T}}_N, \bar{\mathbb{S}}_K],$$

where

$$(3.12) \quad \mathcal{N}_\alpha[\bar{R}, \bar{U}, \bar{\mathbb{T}}_N, \bar{\mathbb{S}}_K] := \frac{1}{(\tau \circ \alpha)^2} \nabla^2 : (\bar{R}\bar{U} \otimes \bar{U})$$

$$+ \operatorname{div}\left(\left(P'\left(\frac{\theta\bar{R}}{(\tau\circ\alpha)^d}\right) - P'(0)\right)\nabla\bar{R}\right)$$

$$+ \nabla^2 : \left(\frac{\nu}{(\tau \circ \alpha)^2}\sqrt{\bar{R}}\bar{\mathbb{S}}_N + \frac{\varepsilon^2}{2(\tau \circ \alpha)^2}\bar{\mathbb{S}}_K\right) + \nu\frac{\dot{\tau} \circ \alpha}{\tau \circ \alpha}\Delta\bar{R},$$

and the same compatibility conditions between overlined quantities as in (2.11)–(2.12). We also remark that we have

$$\operatorname{div}\left(\left(P'\left(\frac{\theta\bar{R}}{(\tau\circ\alpha)^d}\right) - P'(0)\right)\nabla\bar{R}\right) = \frac{(\tau \circ \alpha)^d}{\theta}\Delta\left(P(\sigma) - \sigma P'(0)\right)\Big|_{\sigma=\frac{\theta\bar{R}}{(\tau\circ\alpha)^d}}.$$

In view of Lemma 3.3, $(\bar{R}, \bar{U})$ verifies for some constant $C_0 > 0$

$$(3.13) \qquad \sup_{s\geqslant 0} \int_{\mathbb{R}^d} \bar{R}(1 + |y|^2 + |\ln\bar{R}|)\,\mathrm{d}y \leqslant C_0,$$

and we also have, by the assumption $\int_0^\infty \mathcal{D}(t)\mathrm{d}t < \infty$,

$$(3.14) \quad \int_0^\infty \left(\frac{\dot{\tau} \circ \alpha}{\tau \circ \alpha}\right)^2 \left(\left\|\sqrt{\bar{R}}\bar{U}\right\|_{L^2(\mathbb{R}^d)}^2 + \varepsilon^2 \left\|\nabla\sqrt{\bar{R}}\right\|_{L^2(\mathbb{R}^d)}^2\right)\mathrm{d}s$$

$$+ \int_0^\infty (\dot{\tau} \circ \alpha)^2(\tau \circ \alpha)^d \left(\int_{\mathbb{R}^d} (P(\sigma) - \sigma P'(0))\Big|_{\sigma=\frac{\bar{R}}{(\tau\circ\alpha)^d}}\,\mathrm{d}y\right)\mathrm{d}s$$

$$+ \nu\int_0^\infty \frac{\dot{\tau} \circ \alpha}{(\tau \circ \alpha)^3}\left\|\bar{\mathbb{S}}_N\right\|_{L^2(\mathbb{R}^d)}^2\,\mathrm{d}s \leqslant C_1,$$

for some constant $C_1 > 0$.

Step 3. — Let $s \in [0,1]$ and consider a sequence $s_n \to \infty$ when $n \to \infty$. Define the sequences $\bar{R}_n(s,y) := \bar{R}(s+s_n,y)$, $\bar{U}_n(s,y) := \bar{U}(s+s_n,y)$, $\bar{\mathbb{T}}_{N,n} := \bar{\mathbb{T}}_N(s+s_n,y)$, $\bar{\mathbb{S}}_{K,n} := \bar{\mathbb{S}}_K(s+s_n,y)$ and $\alpha_n(s) := \alpha(s+s_n)$, in such a way that

$$(3.15) \quad \partial_s \bar{R}_n - \frac{2P'(0)}{(\dot{\tau} \circ \alpha_n)^2} \partial_s \bar{R}_n + \frac{P'(0)}{(\dot{\tau} \circ \alpha_n)^2} \partial_s^2 \bar{R}_n = \mathcal{L}\bar{R}_n + \mathcal{N}_{\alpha_n}[\bar{R}_n, \bar{U}_n, \bar{\mathbb{T}}_{N,n}, \bar{\mathbb{S}}_{K,n}].$$

Moreover, estimates (3.13) and (3.14) yield

$$(3.16) \qquad\qquad \sup_{n \in \mathbb{N}} \sup_{s \in [0,1]} \int_{\mathbb{R}^d} \bar{R}_n(1 + |y|^2 + |\ln \bar{R}_n|) \mathrm{d}y \leqslant C,$$

and

$$\lim_{n \to \infty} \int_0^1 \left(\frac{\dot{\tau} \circ \alpha_n}{\tau \circ \alpha_n}\right)^2 \left(\left\|\sqrt{\bar{R}_n}\bar{U}_n\right\|_{L^2(\mathbb{R}^d)}^2 + \varepsilon^2 \left\|\nabla\sqrt{\bar{R}_n}\right\|_{L^2(\mathbb{R}^d)}^2\right) \mathrm{d}s = 0,$$

$$(3.17) \qquad \lim_{n \to \infty} \int_0^1 (\dot{\tau} \circ \alpha_n)^2 (\tau \circ \alpha_n)^d \left(\int_{\mathbb{R}^d} (P(\sigma) - \sigma P'(0))\Big|_{\sigma = \frac{\theta\bar{R}}{(\tau \circ \alpha_n)^d}} \mathrm{d}y\right) \mathrm{d}s = 0,$$

$$\lim_{n \to \infty} \nu \int_0^1 \frac{\dot{\tau} \circ \alpha_n}{(\tau \circ \alpha_n)^3} \left\|\bar{\mathbb{S}}_{N,n}\right\|_{L^2(\mathbb{R}^d)}^2 \mathrm{d}s = 0.$$

From (3.16) and Dunford–Pettis theorem, we deduce that there exists

$$R_\infty \in L^1((0,1) \times \mathbb{R}^d)$$

such that (up to extracting a subsequence)

$$\bar{R}_n \rightharpoonup R_\infty \text{ weakly in } L^1((0,1) \times \mathbb{R}^d) \text{ as } n \to \infty,$$

with R_∞ of finite (mean) relative entropy $\int_0^1 \int_{\mathbb{R}^d} |R_\infty \ln(R_\infty/\Gamma)| < \infty$.

Therefore, passing to the limit $n \to \infty$ in Equation (3.15), we obtain

$$(3.18) \qquad\qquad \partial_s R_\infty = \mathcal{L}R_\infty \text{ in } \mathcal{D}'((0,1) \times \mathbb{R}^d).$$

In order to establish (3.18), the convergence of the second, third and fourth terms of (3.15) are evident, hence we only give the details for the convergence of the term $\mathcal{N}_{\alpha_n}[\bar{R}_n, \bar{U}_n, \bar{\mathbb{T}}_{N,n}, \bar{\mathbb{S}}_{K,n}]$ in $\mathcal{D}'((0,1) \times \mathbb{R}^d)$. For any $\phi \in \mathcal{D}((0,1) \times \mathbb{R}^d)$ we have

$$\left|\left\langle \frac{1}{(\tau \circ \alpha_n)^2}\nabla^2 : (\bar{R}_n\bar{U}_n \otimes \bar{U}_n), \phi \right\rangle\right| = \left|\int_0^1 \int_{\mathbb{R}^d} \frac{1}{(\tau \circ \alpha_n)^2}(\bar{R}_n\bar{U}_n \otimes \bar{U}_n) : \nabla^2\phi \, \mathrm{d}y \, \mathrm{d}s\right|$$

$$\lesssim \left(\sup_{s \in [0,1]} \frac{1}{(\dot{\tau} \circ \alpha_n)^2}\right) \left(\int_0^1 \left(\frac{\dot{\tau} \circ \alpha_n}{\tau \circ \alpha_n}\right)^2 \|\sqrt{\bar{R}_n}\bar{U}_n\|_{L^2(\mathbb{R}^d)}^2 \, \mathrm{d}s\right),$$

from which we deduce, using (3.16) and (3.17), the convergence of the first term of $\mathcal{N}_{\alpha_n}[\bar{R}_n, \bar{U}_n, \bar{\mathbb{T}}_{N,n}, \bar{\mathbb{S}}_{K,n}]$, that is

$$\lim_{n \to \infty} \frac{1}{(\tau \circ \alpha_n)^2}\nabla^2 : (\bar{R}_n\bar{U}_n \otimes \bar{U}_n) = 0 \text{ in } \mathcal{D}'((0,1) \times \mathbb{R}^d).$$

For the second term, we write

$$
\left| \left\langle \operatorname{div}\left((P'(\tfrac{\theta \bar{R}_n}{(\tau \circ \alpha_n)^d}) - P'(0))\nabla \bar{R}_n \right), \phi \right\rangle \right|
$$

$$
= \left| \int_0^1 \int_{\mathbb{R}^d} (\tau \circ \alpha_n)^d \left(P(\sigma) - \sigma P'(0) \right) \Big|_{\sigma = \frac{\theta \bar{R}_n}{(\tau \circ \alpha_n)^d}} \Delta \phi \, \mathrm{d}y \, \mathrm{d}s \right|
$$

$$
\lesssim \left(\sup_{s \in [0,1]} \frac{1}{(\dot{\tau} \circ \alpha_n)^2} \right) \left(\int_0^1 \int_{\mathbb{R}^d} (\dot{\tau} \circ \alpha_n)^2 (\tau \circ \alpha_n)^d \left(P(\sigma) - \sigma P'(0) \right) \Big|_{\sigma = \frac{\theta \bar{R}_n}{(\tau \circ \alpha_n)^d}} \mathrm{d}y \, \mathrm{d}s \right),
$$

which again converges to 0 thanks to (3.16) and (3.17). Concerning the third term, we recall first the compatibility condition $\bar{\mathbb{S}}_{K,n} = \sqrt{\bar{R}_n} \nabla^2 \bar{R}_n - \nabla \sqrt{\bar{R}_n} \otimes \nabla \sqrt{\bar{R}_n}$ from (2.12), from which we obtain

$$
\varepsilon^2 \left| \left\langle \frac{1}{(\tau \circ \alpha_n)^2} \nabla^2 : \bar{\mathbb{S}}_{K,n}, \phi \right\rangle \right|
$$

$$
\lesssim \varepsilon^2 \int_0^1 \int_{\mathbb{R}^d} \frac{1}{(\tau \circ \alpha_n)^2} \left(\left| \nabla \sqrt{\bar{R}_n} \right|^2 + |\bar{R}_n| \right) (|\nabla^2 \phi| + |\nabla^3 \phi|) \, \mathrm{d}y \, \mathrm{d}s
$$

$$
\lesssim \varepsilon^2 \left(\sup_{s \in [0,1]} \frac{1}{(\dot{\tau} \circ \alpha_n)^2} \right) \left(\int_0^1 \left(\frac{\dot{\tau} \circ \alpha_n}{\tau \circ \alpha_n} \right)^2 \left\| \nabla \sqrt{\bar{R}_n} \right\|^2_{L^2(\mathbb{R}^d)} \, \mathrm{d}s \right)
$$

$$
+ \varepsilon^2 \left(\sup_{s \in [0,1]} \frac{1}{(\tau \circ \alpha_n)^2} \right) \sup_{n \in \mathbb{N}} \sup_{s \in [0,1]} \| \bar{R}_n \|_{L^1(\mathbb{R}^d)},
$$

which goes to 0 using (3.16) and (3.17). For the fourth term of $\mathcal{N}_{\alpha_n}[\bar{R}_n, \bar{U}_n, \bar{\mathbb{T}}_{N,n}, \bar{\mathbb{S}}_{K,n}]$, we have

$$
\left| \nu \left\langle \frac{1}{(\tau \circ \alpha_n)^2} \nabla^2 : (\sqrt{\bar{R}_n} \bar{\mathbb{S}}_{N,n}), \phi \right\rangle \right| = \nu \left| \int_0^1 \int_{\mathbb{R}^d} \frac{1}{(\tau \circ \alpha_n)^2} \sqrt{\bar{R}_n} \bar{\mathbb{S}}_{N,n} : \nabla^2 \phi \, \mathrm{d}y \, \mathrm{d}s \right|
$$

$$
\lesssim \nu \left| \int_0^1 \int_{\mathbb{R}^d} \frac{1}{(\tau \circ \alpha_n)^2} \sqrt{\bar{R}_n} |\bar{\mathbb{S}}_{N,n}| \, |\nabla^2 \phi| \, \mathrm{d}y \, \mathrm{d}s \right|
$$

$$
\lesssim \nu \left(\int_0^1 \frac{1}{(\tau \circ \alpha_n)(\dot{\tau} \circ \alpha_n)} \left\| \sqrt{\bar{R}_n} \right\|^2_{L^2(\mathbb{R}^d)} \, \mathrm{d}s \right)^{\frac{1}{2}} \left(\int_0^1 \frac{\dot{\tau} \circ \alpha_n}{(\tau \circ \alpha_n)^3} \| \bar{\mathbb{S}}_{N,n} \|^2_{L^2(\mathbb{R}^d)} \, \mathrm{d}s \right)^{\frac{1}{2}}
$$

$$
\lesssim \nu \left(\sup_{n \in \mathbb{N}} \sup_{s \in [0,1]} \frac{1}{(\dot{\tau} \circ \alpha_n)(\tau \circ \alpha_n)} \right) \left(\sup_{n \in \mathbb{N}} \sup_{s \in [0,1]} \| \bar{R}_n \|_{L^1(\mathbb{R}^d)} \right)
$$

$$
\times \left(\int_0^1 \frac{\dot{\tau} \circ \alpha_n}{(\tau \circ \alpha_n)^3} \| \bar{\mathbb{S}}_{N,n} \|^2_{L^2(\mathbb{R}^d)} \, \mathrm{d}s \right)^{\frac{1}{2}}.
$$

That last expression converges to 0. For the last term of $\mathcal{N}_{\alpha_n}[\bar{R}_n, \bar{U}_n, \bar{\mathbb{T}}_{N,n}, \bar{\mathbb{S}}_{K,n}]$, we obtain finally

$$
\nu \left| \left\langle \frac{\dot{\tau} \circ \alpha_n}{\tau \circ \alpha_n} \Delta \bar{R}_n, \phi \right\rangle \right| = \nu \left| \int_0^1 \int_{\mathbb{R}^d} \frac{\dot{\tau} \circ \alpha_n}{\tau \circ \alpha_n} \bar{R}_n \Delta \phi \, \mathrm{d}y \, \mathrm{d}s \right|
$$

$$
\lesssim \nu \left(\sup_{s \in [0,1]} \frac{\dot{\tau} \circ \alpha_n}{\tau \circ \alpha_n} \right) \left(\sup_{n \in \mathbb{N}} \sup_{s \in [0,1]} \| \bar{R}_n \|_{L^1(\mathbb{R}^d)} \right),
$$

which also goes to 0.

Step 4. — We now follow the arguments of [CG18] in order to show that $R_\infty = \Gamma$, which concludes the proof of point (2). Because R_∞ has finite entropy and, by a tightness argument, $\bar{R}_n$ cannot lose mass thanks to (3.16), [AMTU01, Corollary 2.17] entail that the solution to (3.18) satisfies

$$\|R_\infty(s) - \Gamma\|_{L^1(\mathbb{R}^d)} \xrightarrow[s\to\infty]{} 0,$$

since R_∞ and Γ have the same mass in view of (2.7). On the other hand, in the s-variable we have

$$\partial_s \bar{R} + \frac{\dot{\tau} \circ \alpha}{P'(0)\tau \circ \alpha} \operatorname{div}(\bar{R}\bar{U}) = 0,$$

and (3.17) implies

$$\frac{\dot{\tau} \circ \alpha}{\tau \circ \alpha} \operatorname{div}(\bar{R}_n \bar{U}_n) \to 0 \text{ in } L^2((0,1); W^{-1,1}(\mathbb{R}^d)) \text{ as } n \to \infty.$$

Therefore $\partial_s R_\infty = 0$, hence $R_\infty = \Gamma$. Since the limit is unique, no extraction of a subsequence is needed, and the result does not depend on the sequence $s_n \to \infty$, hence the result.

(3). — The last point of Theorem 2.11 is proven by rewriting the energy E, defined by (1.5), in terms of the new unknowns (R, U) via (2.7):

$$E(t) = \frac{1}{2} \int \rho(t,x)|u(t,x)|^2 \mathrm{d}x + \frac{\varepsilon^2}{2} \int \left|\nabla\sqrt{\rho(t,x)}\right|^2 \mathrm{d}x + \int F(\rho(t,x))\mathrm{d}x$$

$$= \frac{\theta}{2\tau^2} \int R(t,y)|U(t,y)|^2 \mathrm{d}y + \frac{\theta(\dot{\tau})^2}{2} \int R(t,y)|y|^2 \mathrm{d}y + \theta\frac{\dot{\tau}}{\tau} \int R(t,y)y \cdot U(t,y)\mathrm{d}y$$

$$+ \theta\frac{\varepsilon^2}{2} \int \left|\nabla\sqrt{R(t,y)}\right|^2 \mathrm{d}y + \int F\left(\frac{\theta}{\tau^d} R\left(t, \frac{x}{\tau^d}\right)\right) \mathrm{d}x.$$

Recalling the identity (2.16),

$$F(\rho) = P'(0)\rho\ln\rho + G(\rho),$$

we can write

$$E(t) = \frac{\theta}{2\tau^2} \int R(t,y)|U(t,y)|^2 \mathrm{d}y + \frac{\theta(\dot{\tau})^2}{2} \int R(t,y)|y|^2 \mathrm{d}y + \theta\frac{\dot{\tau}}{\tau} \int R(t,y)y \cdot U(t,y)\mathrm{d}y$$

$$+ \theta\frac{\varepsilon^2}{2} \int \left|\nabla\sqrt{R(t,y)}\right|^2 \mathrm{d}y + \theta P'(0) \int R(t,y)\ln R(t,y)\mathrm{d}y$$

$$+ \theta P'(0)\ln\frac{\theta}{\tau^d} \int R(t,y)\mathrm{d}y + \tau^d \int G\left(\frac{\theta}{\tau^d} R(t,y)\right) \mathrm{d}y.$$

In view of Lemma 3.3, the first, fourth, fifth and last terms are bounded functions of time. Invoking in addition Cauchy–Schwarz inequality, the third term is $\mathcal{O}(\dot{\tau}) = \mathcal{O}(\sqrt{\ln t})$ from Lemma 2.5. Therefore, since we have assumed $E(t) = o(\ln t)$, we infer

$$\frac{(\dot{\tau})^2}{2} \int R(t,y)|y|^2 \mathrm{d}y - P'(0)\ln\tau^d \int R(t,y)\mathrm{d}y = o(\ln t) \quad \text{as } t \to \infty.$$

Lemma 2.5 yields

$$\dot{\tau} = 2\sqrt{P'(0)\ln t}\,(1 + o(1))\,, \quad \ln\tau = (1 + o(1))\ln t,$$

therefore

$$2 \int R(t,y)|y|^2 \mathrm{d}y - d \int R(t,y)\mathrm{d}y \xrightarrow[t\to\infty]{} 0.$$

Recalling that the mass is conserved, and an easy property of the Gaussian Γ,

$$\int R(t,y)\mathrm{d}y = \int R(0,y)\mathrm{d}y = \int \Gamma(y)\mathrm{d}y, \quad \int |y|^2 \Gamma(y)\mathrm{d}y = \frac{d}{2} \int \Gamma(y)\mathrm{d}y,$$

the proof of the last point of Theorem 2.11 follows. $\qquad\square$

4. On the notion of weak solutions

In this part, we investigate the notion of weak solutions that we consider for the long-time analysis. At first, we provide a priori estimates satisfied by classical solutions to (1.4) such that the density decays sufficiently fast at infinity. These estimates justify the regularity statements of Definition 2.6. Second, we prove sequential compactness of bounded sets of weak solutions. Classically, this compactness result is a cornerstone for obtaining existence of weak solutions.

4.1. A priori estimates

In this section, we present some a priori estimates that motivate our definition of weak solution. As we noticed before, the structure of (2.8) suits better a priori estimates than (1.4). So, from now on, we consider solutions (R,U) of the system written in this form.

4.1.1. Energy estimate

First, we have an extension of Lemma 3.3.

PROPOSITION 4.1. — *Consider $\varepsilon, \nu \geqslant 0$. Assume that the initial data satisfies*

$$R_0(1 + |y|^2 + \ln R_0) \in L^1, \quad \sqrt{R_0}U_0 \in L^2, \quad \varepsilon \nabla \sqrt{R_0} \in L^2.$$

Let (R,U) be a smooth solution to (2.8) associated to the initial data (R_0, U_0), then

(4.1)
$$R(1 + |y|^2 + \ln R) \in L^\infty(\mathbb{R}^+; L^1(\mathbb{R}^d)),$$
$$\frac{1}{\tau}\sqrt{R}U \in L^\infty(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$
$$\frac{\varepsilon}{\tau}\nabla\sqrt{R} \in L^\infty(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$
$$\sqrt{\frac{\dot{\tau}}{\tau^3}}\sqrt{R}U \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$
$$\varepsilon\sqrt{\frac{\dot{\tau}}{\tau^3}}\nabla\sqrt{R} \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$
$$\frac{\sqrt{\nu}}{\tau^2}\sqrt{R}DU \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)).$$

Proof. — In the same vein as in Remark 2.13, we first remark that

$$\frac{\nu\dot{\tau}}{\tau^3} \int R|\operatorname{div} U| \leqslant C\frac{\nu\dot{\tau}^2}{\tau^2} \int R + \frac{1}{2}\frac{\nu}{\tau^4} \int R|DU|^2 \leqslant C\frac{\nu\dot{\tau}^2}{\tau^2} \int R + \frac{1}{2}\mathcal{D}.$$

Therefore, using (2.14), the conservation of mass and the fact that $\int \frac{\dot{\tau}^2}{\tau^2} < \infty$, we obtain that the pseudo energy $\mathcal{E}$ is uniformly bounded from above. Lemma 3.3 implies that $\mathcal{E}$ is uniformly bounded in time, and its nonnegative dissipation $\mathcal{D}$ is integrable in time, which gives the desired a priori bounds on (R, U).   □

4.1.2. Pseudo entropy and effective velocity

Contrary to the Newtonian case, the previous a priori estimate is not sufficient to run a classical compactness argument for proving existence of solutions. So, we provide here a further estimate satisfied by a "pseudo entropy" of an effective velocity. This construction is inspired of [AS18]. Given $\lambda \in \mathbb{R}$, define the effective velocity

$$W_\lambda = U + \lambda \nabla \ln R.$$

Then the pair (R, W_λ) satisfies

$$(4.2) \quad \begin{cases} \partial_t R + \dfrac{1}{\tau^2} \operatorname{div}(RW_\lambda) = \dfrac{\lambda}{\tau^2}\Delta R, \\[2mm] \partial_t(RW_\lambda) + \dfrac{1}{\tau^2}\operatorname{div}(RW_\lambda \otimes W_\lambda) + 2P'(0)yR + P'\left(\dfrac{\theta R}{\tau^d}\right)\nabla R \\[2mm] \qquad = \dfrac{\lambda_1}{2\tau^2}R\nabla\left(\dfrac{\Delta\sqrt{R}}{\sqrt{R}}\right) + \dfrac{\lambda_2}{\tau^2}\operatorname{div}(RDW_\lambda) + \dfrac{\lambda}{\tau^2}\Delta(RW_\lambda) + \dfrac{\nu\dot{\tau}}{\tau}\nabla R, \end{cases}$$

where $\lambda_1 := 4\lambda^2 - 4\nu\lambda + \varepsilon^2$ and $\lambda_2 := \nu - 2\lambda$.

Remark 4.2. — If $0 \leqslant \varepsilon < \nu$, we define $\lambda := \frac{\nu - \sqrt{\nu^2 - \varepsilon^2}}{2} \geqslant 0$ so that $\lambda_1 = 0$ and $\lambda_2 = \sqrt{\nu^2 - \varepsilon^2} > 0$. Then (R, W_λ) satisfies

$$(4.3) \quad \begin{cases} \partial_t R + \dfrac{1}{\tau^2} \operatorname{div}(RW_\lambda) = \dfrac{\lambda}{\tau^2}\Delta R, \\[2mm] \partial_t(RW_\lambda) + \dfrac{1}{\tau^2}\operatorname{div}(RW_\lambda \otimes W_\lambda) + 2P'(0)yR + P'\left(\dfrac{\theta R}{\tau^d}\right)\nabla R \\[2mm] \qquad = \dfrac{\lambda_2}{\tau^2}\operatorname{div}(RDW_\lambda) + \dfrac{\lambda}{\tau^2}\Delta(RW_\lambda) + \dfrac{\nu\dot{\tau}}{\tau}\nabla R. \end{cases}$$

We observe that when $\varepsilon = 0$, then $W_\lambda = U$, and (4.3) is just the original equation (2.8) with $\varepsilon = 0$.

We define the pseudo λ-entropy of (R, U) by

$$\mathcal{E}_\lambda := \frac{1}{2\tau^2} \int R|W_\lambda|^2 + \frac{\lambda_1}{2\tau^2} \int |\nabla\sqrt{R}|^2 + P'(0)\int (R|y|^2 + R\ln R) + \frac{\tau^d}{\theta}\int G\left(\frac{\theta R}{\tau^d}\right),$$

and its associated dissipation

$$\mathcal{D}_\lambda := \frac{\dot\tau}{\tau^3} \int \left\{ R|W_\lambda|^2 + \lambda_1 |\nabla\sqrt{R}|^2 \right\} + d\frac{\dot\tau}{\tau}\tau^d \left(\int \left[P(\sigma) - \sigma P'(0) \right]\Big|_{\sigma=\frac{\theta R}{\tau^d}} \right)$$

$$+ \frac{\lambda_2}{\tau^4} \int R|DW_\lambda|^2 + \frac{\lambda}{\tau^4} \int R|\nabla W_\lambda|^2 + \frac{4\lambda P'(0)}{\tau^2} \int |\nabla\sqrt{R}|^2$$

$$+ \frac{4\lambda}{\tau^2} \int \frac{\theta R}{\tau^d} G'' \left(\frac{\theta R}{\tau^d} \right) |\nabla\sqrt{R}|^2 + \frac{\lambda\lambda_1}{4\tau^4} \int R|\nabla^2 \ln R|^2.$$

This is nothing but the pseudo energy and dissipation associated to (4.2).

By reproducing computations of the a priori estimate to this system, we obtain:

LEMMA 4.3. — *Let (R, U) be a smooth solution to (2.8) and consider the effective velocity $W_\lambda := U + \lambda\nabla \ln R$ with $\lambda \in \mathbb{R}$. Then the pseudo λ-entropy $\mathcal{E}_\lambda$ satisfies*

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathcal{E}_\lambda + \mathcal{D}_\lambda = \frac{2\lambda d P'(0)}{\tau^2} \int R - \nu\frac{\dot\tau}{\tau^3} \int R \operatorname{div} W_\lambda.$$

Remark 4.4. — If we set $\lambda = \nu$, we note that $\lambda_1 = \varepsilon^2$ and $\lambda_2 = -\nu$. In this case, two terms in the dissipation combine to yield:

$$\frac{\lambda_2}{\tau^4} \int R|DW_\lambda|^2 + \frac{\lambda}{\tau^4} \int R|\nabla W_\lambda|^2 = \frac{\nu}{\tau^4} \int_R |AW_\lambda|^2 = \frac{\nu}{\tau^4} \int_R |AU|^2.$$

Thus, we recover the BD-entropy estimate associated with our system (see [BD04, BDL03] for the introduction of this method, and [VY16b] in the case with a Bohm potential). We apply only this particular case to obtain the regularity statement below. Nevertheless, we apply the choice of λ from Remark 4.2 in the next subsection (to prove a Mellet–Vasseur estimate). This choice enables to delete the Korteweg term, this is why we provided a statement with a general λ in the previous lemma.

Combining the latter entropy estimate with energy estimate yields controls on (R, U), which enable to consider various cases for the parameters ε and ν. This ensures the following regularity properties of a classical solution:

PROPOSITION 4.5. — *Consider $\varepsilon, \nu \geqslant 0$. Assume that the initial data satisfies*

$$R_0(1 + |y|^2 + \ln R_0) \in L^1(\mathbb{R}^d), \quad \sqrt{R_0}U_0 \in L^2(\mathbb{R}^d), \quad (\varepsilon + \nu)\nabla\sqrt{R_0} \in L^2(\mathbb{R}^d).$$

Let (R, U) be a smooth solution to (2.8) associated to the initial data (R_0, U_0), then

$$R(1 + |y|^2 + \ln R) \in L^\infty(\mathbb{R}^+; L^1(\mathbb{R}^d)),$$

$$\frac{1}{\tau}\sqrt{R}U \in L^\infty(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

$$\frac{(\varepsilon + \nu)}{\tau}\nabla\sqrt{R} \in L^\infty(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

$$\sqrt{\frac{\dot\tau}{\tau^3}}\sqrt{R}U \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

(4.4)
$$\varepsilon\sqrt{\frac{\dot\tau}{\tau^3}}\nabla\sqrt{R} \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

$$\frac{\sqrt\nu}{\tau}\nabla\sqrt{R} \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

$$\frac{\sqrt\nu}{\tau^2}\sqrt{R}\nabla U \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

$$\frac{\nu}{\tau^2}\frac{\theta R}{\tau^d}G''\left(\frac{\theta R}{\tau^d}\right)|\nabla\sqrt{R}|^2 \in L^1(\mathbb{R}^+; L^1(\mathbb{R}^d)),$$

$$\frac{\varepsilon\sqrt\nu}{\tau^2}\sqrt{R}\nabla^2\log R \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)),$$

and we observe that last estimate implies (see [Jün10, VY16b])

$$\frac{\varepsilon\sqrt\nu}{\tau^2}\nabla^2\sqrt{R} \in L^2(\mathbb{R}^+; L^2(\mathbb{R}^d)), \quad \frac{\varepsilon^{1/2}\nu^{1/4}}{\tau}\nabla R^{\frac{1}{4}} \in L^4(\mathbb{R}^+; L^4(\mathbb{R}^d)).$$

Proof of Proposition 4.5. — From (2.14) and Lemma 4.3 with $\lambda = \nu$, it follows

$$\frac{\mathrm{d}}{\mathrm{d}t}(\mathcal{E}(t) + \mathcal{E}_\nu(t)) + \mathcal{D}(t) + \mathcal{D}_\nu(t) = \frac{2\mathrm{d}\nu}{\tau^2}\int R,$$

and we conclude in a similar way as in the proof of Proposition 4.1, using now that $\int \mathrm{d}t/\tau(t)^2 < \infty$ and recalling that $P'(\sigma) = P'(0) + \sigma G''(\sigma)$ with $P'(0) > 0$ and $G'' \geqslant 0$. $\qquad\square$

4.1.3. Mellet–Vasseur estimate

It turns out that the above estimates are insufficient for the construction of solutions to (1.4) via a compactness approach: the above information does not enable to pass to the limit in the convective term $RU \otimes U$ (see the introduction of [VY16a] for more precise statements). So, when $0 \leqslant \varepsilon \leqslant \nu$, we add a further estimate that we adapt from [MV07, AS18] to the isothermal case. For this, we restrict from now to the isothermal case $P(\rho) \equiv \kappa\rho$.

PROPOSITION 4.6. — *Let $\nu > 0$ and $0 \leqslant \varepsilon \leqslant \nu$, $P(\rho) = \kappa\rho$ with $\kappa > 0$, and $T > 0$. Assume that the initial data satisfy*

$$R_0(1 + |y|^2 + \ln R_0) \in L^1(\mathbb{R}^d), \quad \sqrt{R_0}U_0 \in L^2(\mathbb{R}^d), \quad (\varepsilon + \nu)\nabla\sqrt{R_0} \in L^2(\mathbb{R}^d).$$

Let (R, U) be a smooth solution to (2.8) associated to the initial data (R_0, U_0). Consider $\lambda(\varepsilon) := (\nu - \sqrt{\nu^2 - \varepsilon^2})/2 \geqslant 0$ and define the effective velocity

$$W_\varepsilon := U + \lambda(\varepsilon) \nabla \ln R,$$

so that (R, W_ε) satisfies (4.3). Denote $\varphi_{MV}(z) = (1 + z) \ln(1 + z)$ for $z \geqslant 0$, and suppose further that

$$\int_{\mathbb{R}^d} R_0 \varphi_{MV} \left(|W_{\varepsilon,0}|^2 + |y|^2 \right) \mathrm{d}y < \infty.$$

Then there exists a constant K_T depending only on T and C_0'' depending only on initial data such that

$$\sup_{t \in (0,T)} \left\{ \int_{\mathbb{R}^d} R \varphi_{MV} \left(|W_\varepsilon|^2 + |y|^2 \right) \mathrm{d}y \right\}$$
$$+ \int_0^T \int_{\mathbb{R}^d} R \varphi'_{MV} \left(|W_\varepsilon|^2 + |y|^2 \right) \left\{ \lambda(\varepsilon) |\nabla W_\varepsilon|^2 + \lambda_2(\varepsilon) |D(W_\varepsilon)|^2 \right\} \mathrm{d}y \, \mathrm{d}t \leqslant K_T C_0'',$$

where $\lambda_2(\varepsilon) := \sqrt{\nu^2 - \varepsilon^2} \geqslant 0$.

Remark 4.7. — The functional is not quite the same as in [MV07], where the authors analyze $\varphi_{MV}(|u|^2)$. Considering an effective velocity follows from [AS18]. On the other hand, the introduction of the term $|y|^2$ is due to the presence of term yR in (2.8), which is a specific feature of our approach adapted to the isothermal case, and seems necessary in order to obtain closed estimates.

Proof. — We first remark that, by construction, we have:

$$(4.5) \qquad \varphi'_{MV}(z) = 1 + \ln(1 + z), \qquad z |\varphi''_{MV}(z)| \leqslant 1, \quad \forall\, z \geqslant 0.$$

Given (R, W_ε) a solution to (4.3), we have then:

$$\frac{\mathrm{d}}{\mathrm{d}t} \int R \, \varphi_{MV} \left(|W_\varepsilon|^2 + |y|^2 \right)$$
$$= \int \partial_t R \, \varphi_{MV} \left(|W_\varepsilon|^2 + |y|^2 \right) + 2 \int R \varphi'_{MV} \left(|W_\varepsilon|^2 + |y|^2 \right) W_\varepsilon \cdot \partial_t W_\varepsilon.$$

For conciseness, we drop the arguments of φ_{MV} and its derivative in what follows. We may then rewrite the last integral on the right-hand side by applying that

$$R \partial_t W_\varepsilon = \frac{\lambda(\varepsilon)}{\tau^2} [\Delta(R W_\varepsilon) - (\Delta R) W_\varepsilon] + \frac{\lambda_2(\varepsilon)}{\tau^2} \operatorname{div}(R D(W_\varepsilon))$$
$$+ \frac{\nu \dot{\tau}}{\tau} \nabla R - \kappa \nabla R - 2\kappa y R - \frac{1}{\tau^2} R W_\varepsilon \cdot \nabla W_\varepsilon,$$

from which we obtain

$$(4.6) \qquad \frac{\mathrm{d}}{\mathrm{d}t} \int R \, \varphi_{MV} = \frac{\lambda(\varepsilon)}{\tau^2} I_0 + 2 \frac{\lambda_2(\varepsilon)}{\tau^2} I_1 + 2 \left(\frac{\nu \dot{\tau}}{\tau} - \kappa \right) I_2 + 2 \left(\frac{1}{\tau^2} - 2\kappa \right) I_3,$$

with

$$I_0 = \int \left\{ 2[\Delta(RW_\varepsilon) - (\Delta R)W_\varepsilon] \cdot W_\varepsilon \varphi'_{MV} + \Delta R \varphi_{MV} \right\},$$

$$I_1 = \int \mathrm{div}(RD(W_\varepsilon)) \cdot W_\varepsilon \varphi'_{MV},$$

$$I_2 = \int \nabla R \cdot W_\varepsilon \varphi'_{MV},$$

$$I_3 = \int yR \cdot W_\varepsilon \varphi'_{MV}.$$

We compute bounds above for these integrals by applying standard transformations and application of (4.5). By integrating by parts we obtain

$$I_0 = -\int R|\nabla(|W_\varepsilon|^2)|^2 \varphi''_{MV} - 2\int R|\nabla W_\varepsilon|^2 \varphi'_{MV} + 2\int R(\varphi'_{MV} + 2|y|^2 \varphi''_{MV})$$

$$= -\int R|\nabla(|W_\varepsilon|^2)|^2 \varphi''_{MV} - 2\int R|\nabla W_\varepsilon|^2 \varphi'_{MV} + \mathcal{O}\left(\int R(1 + |y|^2 + |W_\varepsilon|^2) \right).$$

For the term I_1 we have

$$I_1 = -\int R\varphi'_{MV}|D(W_\varepsilon)|^2 + \mathcal{O}\left(\int R(|W_\varepsilon|^2 + |y|^2)|\varphi''_{MV}||D(W_\varepsilon)||\nabla W_\varepsilon| \right)$$

$$= -\int R\varphi'_{MV}|D(W_\varepsilon)|^2 + \mathcal{O}\left(\int R|\nabla W_\varepsilon|^2 \right).$$

We compute I_2 by integrating by parts, which gives

$$I_2 = -\int R \,\mathrm{div}\, W_\varepsilon \,\varphi'_{MV} - 2\int R\left[(W_\varepsilon \cdot \nabla)W_\varepsilon \right] \cdot W_\varepsilon \varphi''_{MV} - 2\int RW_\varepsilon \cdot y\varphi''_{MV},$$

and introducing an absolute constant C and a small parameter $\eta > 0$ to be fixed later on, we obtain

$$|I_2| \leqslant C\left(\int R|D(W_\varepsilon)|\varphi'_{MV} + \int R(|W_\varepsilon|^2 + |y|^2)\varphi''_{MV}|\nabla W_\varepsilon| \right)$$

$$\leqslant \eta \int R\varphi'_{MV}|D(W_\varepsilon)|^2 + \frac{C}{\eta}\left(\int R|\nabla W_\varepsilon|^2 + \int R(1 + \varphi'_{MV}) \right)$$

$$\leqslant \eta \int R\varphi'_{MV}|D(W_\varepsilon)|^2 + \frac{C}{\eta}\left(\int R|\nabla W_\varepsilon|^2 + \int R(1 + |y|^2 + |W_\varepsilon|^2) \right).$$

Concerning I_3, Young inequality yields

$$|I_3| \leqslant \int R|y||W_\varepsilon|\left(\ln\left(1 + |W_\varepsilon|^2 + |y|^2 \right) + 1 \right) \leqslant \int R\left(|y|^2 + |W_\varepsilon|^2 \right) + \int R\varphi_{MV}.$$

We substitute I_0, I_1, I_2 and I_3 with these computations into (4.6), and we remark that τ and $1/\tau$ are uniformly bounded with their derivatives on $[0, T]$. We obtain then that there exist positive constants c_T and C_T depending only on T for which

$$(4.7) \quad \frac{\mathrm{d}}{\mathrm{d}t} \int R\,\varphi_{MV} + c_T \int R\varphi'_{MV}\{\lambda(\varepsilon)|\nabla W_\varepsilon|^2 + \lambda_2(\varepsilon)|D(W_\varepsilon)|^2\}$$
$$\leqslant (C_T(\nu + 1) + \kappa)$$
$$\times \left(\eta \int R\varphi'_{MV}|D(W_\varepsilon)|^2 + \frac{1}{\eta}\left(\int R|\nabla W_\varepsilon|^2 + \int R(1 + |y|^2 + |W_\varepsilon|^2) + \int R\varphi_{MV} \right) \right).$$

Choosing η sufficiently small so that the first term of the right hand side is absorbed by the left hand side, we are in position to apply a Grönwall lemma to $\int R\varphi_{MV}$. We note here that combining the estimates of Propositions 4.1 and 4.5 entails

$$\int_0^T \int_{\mathbb{R}^d} R|\nabla W_\varepsilon|^2 + \int_0^T \int_{\mathbb{R}^d} R(1 + |y|^2 + |W_\varepsilon|^2) \leqslant K_T(C_0 + C_0'),$$

and we obtain

$$\sup_{t\in(0,T)} \int_{\mathbb{R}^d} R\varphi_{MV} \leqslant K_T C_0''.$$

It remains to integrate (4.7) to conclude. $\qquad\square$

Remark 4.8. — We note that, when $\varepsilon > 0$, the choice $\varphi_{MV}(z) = (1 + z)\ln(1 + z)$ is not unique. Indeed, with the term I_0 we control a full gradient of W_ε, while the term I_1 only enables a control of the symmetric part of this gradient. Hence, when $\varepsilon = 0$ we have to choose an entropy such that $z\varphi''_{MV}$ is bounded, and the parasite term appearing in I_1 is controlled with the previous pseudo-entropy estimate. On the other hand, when $\varepsilon > 0$, this Mellet–Vasseur estimate is self-consistent and we can afford entropies φ such that $z\varphi'' \lesssim \varphi'$, typically, any power-like entropy.

Remark 4.9. — The restriction $\varepsilon \leqslant \nu$ is mandatory to enable the choice of a parameter λ such that the Korteweg term disappears in the system for (R, W_λ), see (4.3).

4.2. Compactness of weak solutions

In this section we assume $\nu > 0$ and $0 \leqslant \varepsilon \leqslant \nu$, and we consider the isothermal case $P(\rho) \equiv \kappa\rho$ with $\kappa > 0$. From Section 4.1, any classical solution (R, U) to (2.8) on $(0, T)$ decaying sufficiently fast at infinity satisfies the following a priori estimates:

- The conservation of mass:

$$(4.8) \qquad \sup_{t\in(0,T)} \int_{\mathbb{R}^d} R = M_0$$

  where M_0 is the mass of the initial data,
- From the dissipation of the pseudo energy:

$$(4.9) \quad \sup_{t\in(0,T)} \left\{ \frac{1}{2\tau^2} \int_{\mathbb{R}^d} \left(R|U|^2 + \varepsilon^2|\nabla\sqrt{R}|^2 \right) + \kappa \int_{\mathbb{R}^d} R(|y|^2 + |\ln R|) \right\}$$
$$+ \int_0^T \left(\frac{\dot\tau}{\tau^3} \int_{\mathbb{R}^d} \left(R|U|^2 + \varepsilon^2|\nabla\sqrt{R}|^2 \right) + \frac{\nu}{\tau^4} \int_{\mathbb{R}^d} |\mathbb{S}_N|^2 \right) \mathrm{d}t \leqslant C_0,$$

  where C_0 depends on initial data only.
- From the dissipation of the pseudo BD-entropy:

$$(4.10) \quad \sup_{t\in(0,T)} \left\{ \frac{1}{2\tau^2} \int \left(R|U + \nu\nabla\ln R|^2 + \varepsilon^2|\nabla\sqrt{R}|^2 \right) + \kappa \int R(|y|^2 + |\ln R|) \right\}$$
$$+ \int_0^T \left(\frac{\dot\tau}{\tau^3} \int \left(R|U|^2 + \varepsilon^2|\nabla\sqrt{R}|^2 \right) + \frac{\nu}{\tau^4} \int |\mathbb{A}_N|^2 + \frac{4\nu\kappa}{\tau^2} \int |\nabla\sqrt{R}|^2 \right) \mathrm{d}t$$
$$+ \int_0^T \frac{\nu\varepsilon^2}{4\tau^4} \left(\int R \left| \nabla^2\ln R \right|^2 \right) \mathrm{d}t \leqslant C_0',$$

where C_0' depends again only on initial data and $\mathbb{A}_N$ stands for the skew-symmetric part of $\mathbb{T}_N$.

- The Mellet–Vasseur type inequality: denoting $\varphi_{MV}(z) = (1+z)\ln(1+z)$, there holds

$$(4.11) \quad \sup_{t \in (0,T)} \left\{ \int R\varphi_{MV}\left(|W_\varepsilon|^2 + |y|^2\right) \right\}$$

$$+ \int_0^T \int \varphi_{MV}'\left(|W_\varepsilon|^2 + |y|^2\right)\left\{\lambda(\varepsilon)|\mathbb{T}_N|^2 + \lambda_2(\varepsilon)|\mathbb{S}_N|^2\right\} \leqslant C_{0,T}'',$$

with $C_{0,T}''$ depending only on initial data and T, where hereafter in this section we define the effective velocity W_ε associated to (R, U) by

$$W_\varepsilon := U + \lambda(\varepsilon)\nabla \ln R,$$

where we recall that $\lambda(\varepsilon) = \frac{\nu - \sqrt{\nu^2 - \varepsilon^2}}{2} \geqslant 0$ and $\lambda_2(\varepsilon) = \sqrt{\nu^2 - \varepsilon^2} \geqslant 0$.

We proceed by studying the compactness of weak solutions to (2.8) which satisfy the estimates (4.8)–(4.11). The different arguments follow closely the proof of [MV07, Theorem 2.1].

THEOREM 4.10. — *Assume* $\nu > 0$ *and* $0 \leqslant \varepsilon \leqslant \nu$, $P(\rho) = \kappa\rho$ *with* $\kappa > 0$, *and let* $T > 0$. *Consider* $(\sqrt{R_n}, \sqrt{R_n}U_n)_{n \in \mathbb{N}}$ *a sequence of weak solutions to* (2.8) *satisfying* (4.8)–(4.11) *with constants* $C_0, C_0', C_{0,T}''$ *independent of* $n \in \mathbb{N}$, *and denote by* $\mathbb{S}_{K,n}$ *and* $\mathbb{T}_{N,n}$ *the tensors associated to* $(\sqrt{R_n}, \sqrt{R_n}U_n)$. *Then, there exists* $(\sqrt{R}, \sqrt{R}U)$, *with associated tensors* $\mathbb{S}_K$ *and* $\mathbb{T}_N$, *such that:*

(1) *Up to the extraction of a subsequence,* $(\sqrt{R_n}, \sqrt{R_n}U_n, \mathbb{T}_{N,n})_{n \in \mathbb{N}}$ *satisfy*

$$\sqrt{R_n} \to \sqrt{R} \quad \text{in } C([0,T]; L^2(\mathbb{R}^d)),$$

$$\sqrt{R_n}U_n \to \sqrt{R}U \quad \text{in } L^2(0,T; L^2(\mathbb{R}^d)),$$

$$\mathbb{T}_{N,n} \rightharpoonup \mathbb{T}_N \quad \text{in } L^2(0,T; L^2(\mathbb{R}^d)) - w,$$

(2) $(\sqrt{R}, \sqrt{R}U)$ *is a weak solution to* (2.8) *in the sense of Definition 2.6.*

Proof of Theorem 4.10. — To start with, we remark that, thanks to (4.8)–(4.10), the sequence we consider is bounded in the following respective spaces:

(b1) $(\sqrt{R_n})_n$ is bounded in $L^\infty(0,T; H^1(\mathbb{R}^d) \cap L^2(\mathbb{R}^d; |y|^2\mathrm{d}y))$,
(b2) $(\sqrt{R_n}U_n)_n$ is bounded in $L^\infty(0,T; L^2(\mathbb{R}^d))$,
(b3) $(\mathbb{T}_{N,n})_n$ is bounded in $L^2(0,T; L^2(\mathbb{R}^d))$.
(b4) $(\nabla^2\sqrt{R_n})_n$ is bounded in $L^2(0,T; L^2(\mathbb{R}^d))$ if $\varepsilon > 0$.

Up to the extraction of a subsequence, we can then construct $(\sqrt{R}, \sqrt{R}U, \mathbb{T}_N)$ as the following limits:

(c1) $\sqrt{R_n} \rightharpoonup \sqrt{R}$ in $L^\infty(0,T; H^1(\mathbb{R}^d)) - w*$,
(c2) $\sqrt{R_n}U_n \rightharpoonup \sqrt{R}U$ in $L^\infty(0,T; L^2(\mathbb{R}^d))) - w*$,
(c3) $\mathbb{T}_{N,n} \rightharpoonup \mathbb{T}_N$ in $L^2(0,T; L^2(\mathbb{R}^d)) - w$,
(c4) $\nabla^2\sqrt{R_n} \rightharpoonup \nabla^2\sqrt{R}$ in $L^2(0,T; L^2(\mathbb{R}^d)) - w$ if $\varepsilon > 0$.

We note directly that the non-negativity of $\sqrt{R}$ is preserved in the weak limit.

Step 1. — From (b1) and Sobolev embeddings, we have

(b5) $(\sqrt{R_n})_n$ is bounded in $L^\infty(0, T; L^q(\mathbb{R}^d))$ for all $\begin{cases} q \in [2, \infty) & \text{if } d = 2, \\ q \in [2, 2^*] & \text{if } d \geqslant 3, \end{cases}$

where $2^* = 2d/(d-2)$. Together with (b2), this implies

(b6) $(R_n U_n)_n$ is bounded in $L^\infty(0, T; L^q(\mathbb{R}^d))$ for all $\begin{cases} q \in [1, \infty) & \text{if } d = 2, \\ q \in [1, d'] & \text{if } d \geqslant 3, \end{cases}$

where d' is the Hölder conjugate exponent of d. Recalling the continuity equation satisfied by $\sqrt{R_n}$,

$$\partial_t \sqrt{R_n} = -\frac{1}{\tau^2} \operatorname{div}(\sqrt{R_n} U_n) + \frac{1}{2\tau^2} \operatorname{Trace}(\mathbb{T}_{N,n}),$$

and that τ is uniformly bounded from below on $(0, T)$, the bounds (b1)–(b3) yield that $(\partial_t \sqrt{R_n})_n$ is bounded in $L^2(0, T; H^{-1}(\mathbb{R}^d))$. Consequently, as in [MV07, Lemma 4.1], we apply Aubin–Lions' lemma in the form [Sim87, Corollary 4] with the triplet $H^1(\mathbb{R}^d) \cap L^2(\mathbb{R}^d; |y|^2 dy) \subset L^2(\mathbb{R}^d) \subset H^{-1}(\mathbb{R}^d)$, where the first embedding is compact. This yields that

(c5) $(\sqrt{R_n})_n$ is relatively compact in $C([0, T]; L^2(\mathbb{R}^d))$.

Furthermore, in the case $\varepsilon > 0$, estimates (b1)–(b4) imply that $(\sqrt{R_n})_n$ is bounded in $L^2(0, T; H^2(\mathbb{R}^d))$ which yields, applying Aubin–Lions' lemma again, that

(c5′) $(\sqrt{R_n})_n$ is relatively compact in $L^2(0, T; H^1_{\text{loc}}(\mathbb{R}^d))$ if $\varepsilon > 0$.

Step 2. — The second step of the proof is to obtain the relative compactness of $(R_n U_n)_n$. We remark that, by definition:

$$\nabla(R_n U_n) = \sqrt{R_n} \mathbb{T}_{N,n} + 2\sqrt{R_n} U_n \otimes \nabla \sqrt{R_n}.$$

We combine here (b1)–(b3). This yields that $(\nabla(R_n U_n))_n$ is bounded in $L^2(0, T; L^1(\mathbb{R}^d))$, hence $(R_n U_n)_n$ is bounded in $L^2(0, T; W^{1,1}(\mathbb{R}^d))$ thanks to (b5). As for $\partial_t(R_n U_n)$, we apply the momentum equation to write:

$$\partial_t(R_n U_n) = -\frac{1}{\tau^2} \operatorname{div}\left(\sqrt{R_n} U_n \otimes \sqrt{R_n} U_n\right) - 2\kappa y R_n - \kappa \nabla R_n + \frac{\nu \dot{\tau}}{\tau} \nabla R_n$$
$$+ \frac{\varepsilon^2}{2\tau^2} \operatorname{div} \mathbb{S}_{K,n} + \frac{\nu}{\tau^2} \operatorname{div}\left(\sqrt{R_n} \mathbb{S}_{N,n}\right),$$

where we recall that $\mathbb{S}_{K,n} = \sqrt{R_n} \nabla^2 \sqrt{R_n} - \nabla \sqrt{R_n} \otimes \nabla \sqrt{R_n}$. Again, the bounds on $\sqrt{R_n}$, $\sqrt{R_n} U_n$, $\mathbb{T}_{N,n}$ and $\nabla^2 \sqrt{R_n}$ coming from (b1)–(b4) imply that $\partial_t(R_n U_n)$ is bounded in $L^2(0, T; W^{-1,1}(\mathbb{R}^d))$. So, by the Aubin–Lions' lemma with the triplet $W^{1,1}(K) \subset L^p(K) \subset W^{-1,1}(K)$ for any $p \in [1, d')$ and any compact $K \subset \mathbb{R}^d$, where the first embedding is compact, we obtain that

(c6) $(R_n U_n)_n$ is relatively compact in $L^2(0, T; L^p_{\text{loc}}(\mathbb{R}^d))$ for all $p \in [1, d')$.

In what follows we assume that we have extracted a subsequence (that we do not relabel) so that we have the convergences:

- $\sqrt{R_n} \to \sqrt{R}$ in $C([0,T]; L^2(\mathbb{R}^d))$;
- $R_n U_n \to M$ in $L^2(0,T; L^p_{\mathrm{loc}}(\mathbb{R}^d))$ for any $1 \leqslant p < d'$;
- $\sqrt{R_n} \to \sqrt{R}$ in $L^2(0,T; H^1_{\mathrm{loc}}(\mathbb{R}^d))$ if $\varepsilon > 0$.

We add here that (b5) entails that the sequence $(R_n)_n$ is bounded in $L^\infty(0,T; L^{q/2}(\mathbb{R}^d))$ for any $2 \leqslant q < \infty$ if $d = 2$ and any $2 \leqslant q \leqslant 2^*$ if $d \geqslant 3$, hence it admits (up to the extraction of a subsequence) a weak-$*$ limit. Thanks to the strong convergence (c5) of $(\sqrt{R_n})_n$ we have that

(c7) $R_n \rightharpoonup R$ in $L^\infty(0,T; L^{q/2}(\mathbb{R}^d)) - w*$ for all $\begin{cases} q \in [2,\infty) & \text{if } d = 2, \\ q \in [2,2^*] & \text{if } d \geqslant 3. \end{cases}$

Step 3. — We proceed with defining the asymptotic velocity-field U. For this, we remark first that, for arbitrary $K \subset (0,T) \times \mathbb{R}^d$ there holds, for arbitrary $2 < q < 2^*$ and p such that $1/p = 1/2 + 1/q \in (1 - 1/d, 1)$:

$$\|R_n U_n\|_{L^p(K)} \leqslant \|\sqrt{R_n}\|_{L^q(K)} \|\sqrt{R_n} U_n\|_{L^2((0,T) \times \mathbb{R}^d)}.$$

Taking $K = \{\sqrt{R} = 0\} \cap ((0,T) \times B(0,A))$ for arbitrary $A > 0$ we apply that $\sqrt{R_n} \mathbb{1}_K \to \sqrt{R} \mathbb{1}_K = 0$ in $L^p(K)$ (by (c5)), and is bounded in $L^r(K)$ for arbitrary $r \in (q, 2^*)$ (by (b5)). By interpolation, we conclude that $\sqrt{R_n} \mathbb{1}_K \to 0$ in $L^q(K)$. Recalling that $\|\sqrt{R_n} U_n\|_{L^2((0,T) \times \mathbb{R}^d)}$ remains bounded and that $R_n U_n \mathbb{1}_K \to M$ in $L^p(K)$, we infer that $M = 0$ on $\{\sqrt{R} = 0\}$. So, we set

$$U = \begin{cases} 0 & \text{on } \{\sqrt{R} = 0\}, \\ \dfrac{M}{R} & \text{on } \left((0,T) \times \mathbb{R}^d\right) \setminus \{\sqrt{R} = 0\}. \end{cases}$$

We note here that by construction

$$U = \lim_{n \to \infty} \frac{R_n U_n}{R_n} = \lim_{n \to \infty} \frac{\sqrt{R_n} U_n}{\sqrt{R_n}} \quad \text{a.e. on } \left((0,T) \times \mathbb{R}^d\right) \setminus \{\sqrt{R} = 0\}.$$

In a similar fashion we define the asymptotic effective velocity field W_ε in the case $\varepsilon > 0$. We observe first that

$$R_n U_n + 2\lambda(\varepsilon)\sqrt{R_n}\nabla\sqrt{R_n} \to M + 2\lambda(\varepsilon)\sqrt{R}\nabla\sqrt{R} =: \bar{M}_\varepsilon \text{ a.e. on } (0,T) \times \mathbb{R}^d,$$

and we have $\bar{M}_\varepsilon = 0$ on $\{\sqrt{R} = 0\}$. Hence we set

$$W_\varepsilon = \begin{cases} 0 & \text{on } \{\sqrt{R} = 0\}, \\ \dfrac{M}{R} + 2\lambda(\varepsilon)\dfrac{\sqrt{R}\nabla\sqrt{R}}{R} & \text{on } \left((0,T) \times \mathbb{R}^d\right) \setminus \{\sqrt{R} = 0\}. \end{cases}$$

Step 4. — The last important step is to prove the strong convergence of the sequence $(\sqrt{R_n}U_n)_n$ in $L^2(0,T; L^2_{\mathrm{loc}}(\mathbb{R}^d))$. In order to do so, we work with the effective velocity $W_{\varepsilon,n} = U_n + \lambda(\varepsilon)\nabla \ln R_n$ (which is just equal to U_n when $\varepsilon = 0$). We first

remark that we have a.e. convergence of $R_n \varphi_{MV}(|y|^2 + |W_{\varepsilon,n}|^2)$. Estimate (4.11) with Fatou's Lemma yield

$$\sup_{(0,T)} \int R\varphi_{MV}(|y|^2 + |W_\varepsilon|^2) < \infty.$$

We may now repeat the arguments of [MV07, p. 445–446] and [AS18]. Namely, we first fix $A, A' > 0$, and remark that

$$\sqrt{R_n}W_{\varepsilon,n} = \frac{R_n U_n}{\sqrt{R_n}} + \nabla\sqrt{R_n} \to \frac{M}{\sqrt{R}} + \nabla\sqrt{R} \quad \text{a.e. on } \{\sqrt{R} \neq 0\},$$

as well as $|\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|<A}| \leqslant A\sqrt{R_n} \to 0$ a.e. on $\{\sqrt{R} = 0\}$. Hence we get

$$\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|<A \cap |R_n|<A'} \to \sqrt{R}W_\varepsilon\mathbb{1}_{|W_\varepsilon|<A \cap |R|<A'} \text{ a.e. on } (0,T) \times \mathbb{R}^d.$$

We write, for any compact $K \subset \mathbb{R}^d$,

$$\int_0^T \int_K \left|\sqrt{R_n}U_n - \sqrt{R}U\right|^2$$

$$\leqslant C\int_0^T \int_K \left|\sqrt{R_n}W_{\varepsilon,n} - \sqrt{R}W_\varepsilon\right|^2 + C\lambda^2(\varepsilon)\int_0^T \int_K \left|\nabla\sqrt{R_n} - \nabla\sqrt{R}\right|^2$$

and evaluate each term separately. The second term goes to 0 thanks to (c5′), while for the first term we estimate

$$(4.12) \quad \int_0^T \int_K \left|\sqrt{R_n}W_{\varepsilon,n} - \sqrt{R}W_\varepsilon\right|^2$$

$$\leqslant C\left(\int_0^T \int_K \left|\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|<A \cap |R_n|<A'} - \sqrt{R}W_\varepsilon\mathbb{1}_{|W_\varepsilon|<A \cap |R|<A'}\right|^2\right.$$

$$+ \int_0^T \int_K \left|\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|\geqslant A}\right|^2 + \left|\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|<A\cap|R_n|\geqslant A'}\right|^2$$

$$\left.+ \int_0^T \int_K \left|\sqrt{R}W_\varepsilon\mathbb{1}_{|W_\varepsilon|\geqslant A}\right|^2 + \left|\sqrt{R}W_\varepsilon\mathbb{1}_{|W_\varepsilon|<A\cap|R|>A'}\right|^2\right).$$

For fixed A and A', the first term on the right-hand side of (4.12) converges to 0 when $n \to \infty$, while for the second one we have, introducing $2 < q < 2^*$:

$$\int_0^T \int_K \left|\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|\geqslant A}\right|^2 + \left|\sqrt{R_n}W_{\varepsilon,n}\mathbb{1}_{|W_{\varepsilon,n}|<A\cap|R_n|\geqslant A'}\right|^2$$

$$\leqslant \frac{1}{\ln(1+A^2)}\int_0^T \int_K R_n\varphi_{MV}((|y|^2 + |W_{\varepsilon,n}|^2)/2) + \frac{A^2}{|A'|^{q-2}}\int_0^T \int_K R_n^q$$

$$\leqslant C\left(\frac{1}{\ln(1+A^2)} + \frac{A^2}{|A'|^{2-q}}\right),$$

with a constant C independent of n. Proceeding in a similar way for the third term of (4.12), we obtain that

$$\limsup_{n\to\infty} \int_0^T \int_K \left|\sqrt{R_n}U_n - \sqrt{R}U\right|^2 \leqslant C\left(\frac{1}{\ln(1+A^2)} + \frac{A^2}{|A'|^{2-q}}\right),$$

for arbitrary A and A', which implies the convergence

$$\text{(c8)} \qquad \sqrt{R_n}U_n \to \sqrt{R}U \text{ in } L^2_{\text{loc}}((0,T) \times \mathbb{R}^d).$$

by letting $A' \to \infty$ and then $A \to \infty$. We note here that, by construction $\sqrt{R}U = 0$ where $U = 0$ in particular on the set $\{\sqrt{R} = 0\}$.

We may finally combine (c1)–(c8) to pass to the limit in the continuity and momentum equations satisfied by $(\sqrt{R_n}, \sqrt{R_n}U_n)$ and their associated tensors $\mathbb{S}_{K,n}, \mathbb{T}_{N,n}$, and obtain that the different items of Definition 2.6 are satisfied by the limit $(\sqrt{R}, \sqrt{R}U)$ and their associated tensors $\mathbb{S}_K, \mathbb{T}_N$. $\qquad\square$

Appendix A. On large time behavior for isentropic Euler equations

In this appendix, we prove Theorem 1.1: for the Euler equation with pressure law $P(\rho) = \rho^\gamma$, $\gamma > 1$, there is no such thing as a universal asymptotic profile for the density. In addition, the dispersion associated to global smooth solutions is not the same as in the isothermal case. To see this, we rewrite the arguments from [Ser97], in the simplest case in order to illustrate the above claims. Consider on $\mathbb{R}^d$, $d \geqslant 1$,

$$\text{(A.1)} \qquad \begin{cases} \partial_t \rho + \text{div}\,(\rho u) = 0, \\ \partial_t(\rho u) + \text{div}(\rho u \otimes u) + \kappa \nabla\,(\rho^\gamma) = 0, \end{cases}$$

with $\kappa > 0$ and $1 < \gamma \leqslant 1 + \frac{2}{d}$. Consider the analogue of (2.7),

$$\rho(t,x) = \frac{1}{(1+t)^d}R\left(\frac{t}{1+t}, \frac{x}{1+t}\right), \quad u(t,x) = \frac{1}{1+t}U\left(\frac{t}{1+t}, \frac{x}{1+t}\right) + \frac{x}{1+t}.$$

Denoting by σ and y the time and space variables for (R, U), we readily check that in terms of (R, U), (A.1) is equivalent to

$$\text{(A.2)} \qquad \begin{cases} \partial_\sigma R + \text{div}\,(RU) = 0, \\ \partial_\sigma(RU) + \text{div}(RU \otimes U) + \kappa(1-\sigma)^{d\gamma-d-2}\nabla\,(R^\gamma) = 0. \end{cases}$$

Note that in the case $\gamma = 1 + 2/d$, (R, U) solves exactly (A.1). This algebraic identity can be viewed as the counterpart of the pseudo-conformal transform in the framework of nonlinear Schrödinger equations (see e.g. [Caz03]), after Madelung transform and a semi-classical limit (see e.g. [AM09, AM12, CDS12]). (Leaving out the semi-classical limit, this shows that at least in the case $\gamma = 1 + 2/d$, (A.1) could be replaced by Korteweg equations, with essentially the same conclusions as below.)

The important remark is that the time interval $t \in [0, \infty)$ has been compactified, since it corresponds to $\sigma \in [0, 1)$. Therefore, if the solution of (A.2) is defined (at least) on the time interval $[0, 1]$, going back to the original unknowns yields a global solution to (A.1).

We rewrite (A.2) away from vacuum as:

$$\text{(A.3)} \qquad \begin{cases} \partial_\sigma R + \text{div}\,(RU) = 0, \\ \partial_\sigma U + U \cdot \nabla U + \kappa(1-\sigma)^{d\gamma-d-2}\frac{1}{R}\nabla\,(R^\gamma) = 0. \end{cases}$$

Using the same change of unknown function used to symmetrize (A.1) ([MUK86, Che90]), but in the case of (R, U), that is,

$$\tilde{R} = R^{\frac{\gamma-1}{2}},$$

(A.3) becomes

(A.4)
$$\begin{cases} \partial_\sigma \tilde{R} + U \cdot \nabla \tilde{R} + \dfrac{\gamma-1}{2} \tilde{R} \operatorname{div} U = 0, \\[2mm] \partial_\sigma U + U \cdot \nabla U + \kappa \dfrac{2\gamma}{\gamma-1}(1-\sigma)^{d\gamma-d-2}\tilde{R}\nabla\tilde{R} = 0. \end{cases}$$

Multiplying the second equation by the symmetric positive definite matrix

$$S(\sigma) = \frac{(\gamma-1)^2}{4\kappa\gamma}(1-\sigma)^{d+2-d\gamma}\,\mathrm{I}_d$$

makes the system symmetric.

Case $\gamma = 1+2/d$. — In this case, the symmetrizer is constant. Using the standard results in this framework (see e.g. [Maj84, Tay97]), we infer that if for $s > d/2 + 1$, $\|(\tilde{R}, U)\|_{H^s(\mathbb{R}^d)}$ is sufficiently small at $\sigma = 0$, then (A.4) has a unique solution $(\tilde{R}, U) \in C([0,1]; H^s(\mathbb{R}^d))$. By the same argument, we can actually solve (A.4) backward in time, by prescribing the data at $\sigma = 1$: if these data are sufficiently small, the solution satisfies $(\tilde{R}, U) \in C([0,1]; H^s(\mathbb{R}^d))$. Back to the initial unknowns, we infer Theorem 1.1.

Case $1 < \gamma < 1+2/d$. — In this case, the symmetrizer S goes to zero as $\sigma \to 1$. Setting, for $m > 1 + d/2$ an integer

$$F_m(\sigma) := \sum_{0 \leqslant |\alpha| \leqslant m} \left(\|\partial_y^\alpha \tilde{R}\|_{L^2}^2 + \left\langle \partial_y^\alpha U, S\partial_y^\alpha U \right\rangle_{L^2, L^2} \right),$$

it is proven in [Ser97] that F_m satisfies the differential inequality

$$\frac{\mathrm{d}F_m}{\mathrm{d}\sigma} \leqslant CF_m + C(1-\sigma)^{d\gamma/2-1-d/2}\left(F_m^{3/2} + F_m^{(m+3)/2} \right).$$

Defining $G_m(\sigma) = F_m(\sigma)\exp(-C\sigma)$, we get

$$\frac{\mathrm{d}G_m}{\mathrm{d}\sigma} \lesssim (1-\sigma)^{d\gamma/2-1-d/2}\left(G_m^{3/2} + G_m^{(m+3)/2} \right).$$

Introducing

$$H(G) := \int_1^G \frac{\mathrm{d}g}{g^{3/2} + g^{(m+3)/2}},$$

we have

$$H(G_m(\sigma)) \leqslant H(G_m(0)) + C_1 \int_0^\sigma (1-s)^{d\gamma/2-1-d/2}\,\mathrm{d}s.$$

Since the last integral is convergent as $\sigma \to 1$ (recall that $\gamma > 1$), and

$$H(G_m(\sigma)) \leqslant H(G_m(0)) + \underbrace{C_1 \int_0^1 (1-s)^{d\gamma/2-1-d/2}\,\mathrm{d}s}_{:=C_2}.$$

Noticing that $H(0) = -\infty$, we see that if $\|(\tilde{R}, U)\|_{H^m}$ is sufficiently small, then $(\tilde{R}, U)$ is defined up to $\sigma = 1$ (by contradiction). Again, we can adapt this argument with data at $\sigma = 1$ (replace $G_m(0)$ with $G_m(1)$ in the above estimate), and decrease time to $\sigma = 0$, in order to infer Theorem 1.1. Note that in starting from $\sigma = 1$, we only assume $(\tilde{R}, U)_{|\sigma=1}$ in H^m, with $\|\tilde{R}(1)\|_{H^m}$ small (not necessarily $\|U(1)\|_{H^m}$).

Appendix B. Qualitative study of ordinary differential equations

B.1. Universal dispersion

We sketch the proof of Lemma 2.5, and refer to [CG18] for details. The fact that under the assumptions of Lemma 2.5, (2.6) has a unique local C^2 solution is an immediate consequence of Cauchy–Lipschitz Theorem. Multiplying (2.6) by $\dot{\tau}$ and integrating, we find

$$(\text{B.1}) \qquad\qquad (\dot{\tau})^2 = C + 4\kappa \ln \tau,$$

where the value $C = \beta^2 - 4\kappa \ln \alpha$ is irrelevant for the rest of the discussion. Since the left hand side of (B.1) is non-negative, we readily have

$$\tau(t) \geqslant \exp\left(-\frac{C}{4\kappa}\right) > 0,$$

for all t in the life-span of τ. This shows that the C^2 solution is uniformly convex, and global in time.

Next, we note that τ grows at least linearly in time. Indeed, if $\beta > 0$, then since τ is convex,

$$\tau(t) \geqslant \beta t + \alpha.$$

On the other hand, if $\beta \leqslant 0$, suppose that τ is bounded, $\tau(t) \leqslant M$. Then (2.6) yields

$$\ddot{\tau}(t) \geqslant \frac{2\kappa}{M},$$

hence a contradiction for t large enough. Therefore, we can find $T > 0$ such that $\tau(T) \geqslant 1$ and $\dot{\tau}(T) > 0$, so arguing like above,

$$\tau(t) \geqslant \dot{\tau}(T)(t - T) + \tau(T), \quad \text{and} \quad \dot{\tau}(t) > 0 \quad \forall\, t \geqslant T.$$

From the above discussion, there exists $T \geqslant 0$ such that for $t \geqslant T$, $\dot{\tau}(t) > 0$, and so (B.1) yields

$$(\text{B.2}) \qquad\qquad \dot{\tau}(t) = \sqrt{C + 4\kappa \ln \tau(t)}, \quad t \geqslant T.$$

Separating the variables, we have

$$\frac{\mathrm{d}\tau}{\sqrt{C + 4\kappa \ln \tau}} = \mathrm{d}t,$$

and the change of variable $\sigma = \sqrt{C + 4\kappa \ln \tau}$ yields

$$\int \frac{\mathrm{d}\tau}{\sqrt{C + 4\kappa \ln \tau}} = \frac{1}{2\kappa} \int e^{(\sigma^2 - C)/4\kappa} \mathrm{d}\sigma.$$

The asymptotic expansion of Dawson function (see e.g. [AS64]) yields, in the sense of diverging integrals,

$$\int e^{\sigma^2} d\sigma \sim \frac{1}{2\sigma} e^{\sigma^2}.$$

We get

$$\frac{\tau(t)}{\sqrt{C + 4\kappa \ln \tau}} \underset{t \to \infty}{\sim} t, \quad \text{hence} \quad \frac{\tau(t)}{\sqrt{4\kappa \ln \tau}} \underset{t \to \infty}{\sim} t.$$

We see here that the initial data of τ, appearing in the numerical value of C, are irrelevant for the leading order large time behavior of τ. We readily infer

$$\tau(t) \underset{t \to \infty}{\sim} 2t\sqrt{\kappa \ln t}, \quad \dot{\tau}(t) \underset{t \to \infty}{\sim} 2\sqrt{\kappa \ln t},$$

where the second relation stems from the first one and (B.2).

B.2. Perturbed dynamics

The proof of Lemma 3.2 resume several of the above steps. Local existence follows again from the Cauchy–Lipschitz Theorem. Leaving out the explicit dependence upon ε and ν in the notation, and multiplying (3.11) by $\dot{\tau}$, integration now yields

$$(B.3) \qquad (\dot{\tau}(t))^2 = C + 4\kappa \ln \tau(t) - \frac{\varepsilon^2}{2\tau(t)^2} - \nu \int_0^t \left(\frac{\dot{\tau}(s)}{\tau(s)}\right)^2 ds.$$

Writing

$$C + 4\kappa \ln \tau(t) = (\dot{\tau}(t))^2 + \frac{\varepsilon^2}{2\tau(t)^2} + \nu \int_0^t \left(\frac{\dot{\tau}(s)}{\tau(s)}\right)^2 ds \geqslant 0,$$

we still have $\tau(t) \geqslant e^{-C/4\kappa} > 0$.

Now suppose that $\tau \in L^\infty(\mathbb{R}_+)$. Then (B.3) and the above property imply

$$(\dot{\tau}(t))^2 + \nu \int_0^t \left(\frac{\dot{\tau}(s)}{\tau(s)}\right)^2 ds \in L^\infty(\mathbb{R}_+),$$

hence

$$(\dot{\tau}(t))^2 + \frac{\nu}{\|\tau\|_{L^\infty}^2} \int_0^t (\dot{\tau}(s))^2 ds \in L^\infty(\mathbb{R}_+).$$

In particular, $\int_0^\infty (\dot{\tau})^2 < \infty$. Integrating by parts,

$$\int_0^t (\dot{\tau}(s))^2 ds = \tau(t)\dot{\tau}(t) - \alpha\beta - \int_0^t \tau\ddot{\tau}$$

$$= \tau(t)\dot{\tau}(t) - \alpha\beta - \int_0^t \left(2\kappa + \frac{\varepsilon^2}{\tau^2} - \nu\frac{\dot{\tau}}{\tau}\right)$$

$$= \tau(t)\dot{\tau}(t) - \alpha\beta - \int_0^t \left(2\kappa + \frac{\varepsilon^2}{\tau^2}\right) + \nu \ln\left(\frac{\tau(t)}{\alpha}\right).$$

Since τ is bounded, we infer

$$\tau(t)\dot{\tau}(t) \gtrsim t - 1,$$

hence a contradiction. Therefore, there exists $t_n \to \infty$ such that

$$\tau(t_n) \xrightarrow[n \to \infty]{} \infty.$$

Now we suppose that

(B.4)
$$\int_0^\infty \left(\frac{\dot{\tau}(s)}{\tau(s)} \right)^2 \mathrm{d}s = \infty.$$

Then (B.3) implies

(B.5)
$$4\kappa \ln \tau(t) - (\dot{\tau}(t))^2 \xrightarrow[t \to \infty]{} \infty.$$

Integrating by parts yields

$$
\begin{aligned}
\int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^2 &= \left. \frac{\dot{\tau}}{\tau} \right|_{t_n}^t - \int_{t_n}^t \dot{\tau} \left(\frac{\ddot{\tau}}{\tau^2} - 2\frac{(\dot{\tau})^2}{\tau^3} \right) \\
&= \left. \frac{\dot{\tau}}{\tau} \right|_{t_n}^t + 2\int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^3 - \int_{t_n}^t \left(2\kappa \frac{\dot{\tau}}{\tau^3} + \varepsilon^2 \frac{\dot{\tau}}{\tau^5} - \nu \frac{(\dot{\tau})^2}{\tau^4} \right) \\
&= \frac{\dot{\tau}}{\tau} + \frac{\kappa}{\tau^2} - \left. \frac{\varepsilon^2}{4\tau^4} \right|_{t_n}^t + 2\int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^3 + \nu \int_{t_n}^t \frac{(\dot{\tau})^2}{\tau^4}.
\end{aligned}
$$

In view of (B.5), the above three integrated terms are bounded. We infer

$$\int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^2 \leqslant C + \left(2\sup_{s \geqslant t_n} \left| \frac{\dot{\tau}(s)}{\tau(s)} \right| + \nu \sup_{s \geqslant t_n} \frac{1}{\tau(s)^2} \right) \int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^2.$$

Now (B.5) yields, for $t \geqslant t_n \gg 1$,

$$\int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^2 \leqslant C + \frac{1}{2} \int_{t_n}^t \left(\frac{\dot{\tau}}{\tau} \right)^2.$$

This provides a contradiction with (B.4). We infer that τ is not bounded, and

$$\int_0^\infty \left(\frac{\dot{\tau}(s)}{\tau(s)} \right)^2 \mathrm{d}s < \infty.$$

But (B.3) shows that for any sequence of time along which τ goes to infinity, $(\dot{\tau})^2$ also goes to infinity. Therefore,

$$\tau(t) \xrightarrow[t \to \infty]{} \infty \quad \text{and} \quad \dot{\tau}(t) \xrightarrow[t \to \infty]{} \infty.$$

For large time, (B.3) becomes

$$(\dot{\tau}(t))^2 \underset{t \to \infty}{\sim} 4\kappa \ln \tau(t),$$

and we can resume the computation of the above subsection to infer Lemma 3.2.

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Rémi CARLES
Univ. Rennes, CNRS, IRMAR - UMR 6625
35000 Rennes (France)
remi.carles@math.cnrs.fr

Kleber CARRAPATOSO
Institut Montpelliérain Alexander Grothendieck
CNRS, Univ. Montpellier (France)
kleber.carrapatoso@umontpellier.fr

Matthieu HILLAIRET
Institut Montpelliérain Alexander Grothendieck
CNRS, Univ. Montpellier (France)
matthieu.hillairet@umontpellier.fr